

DTU



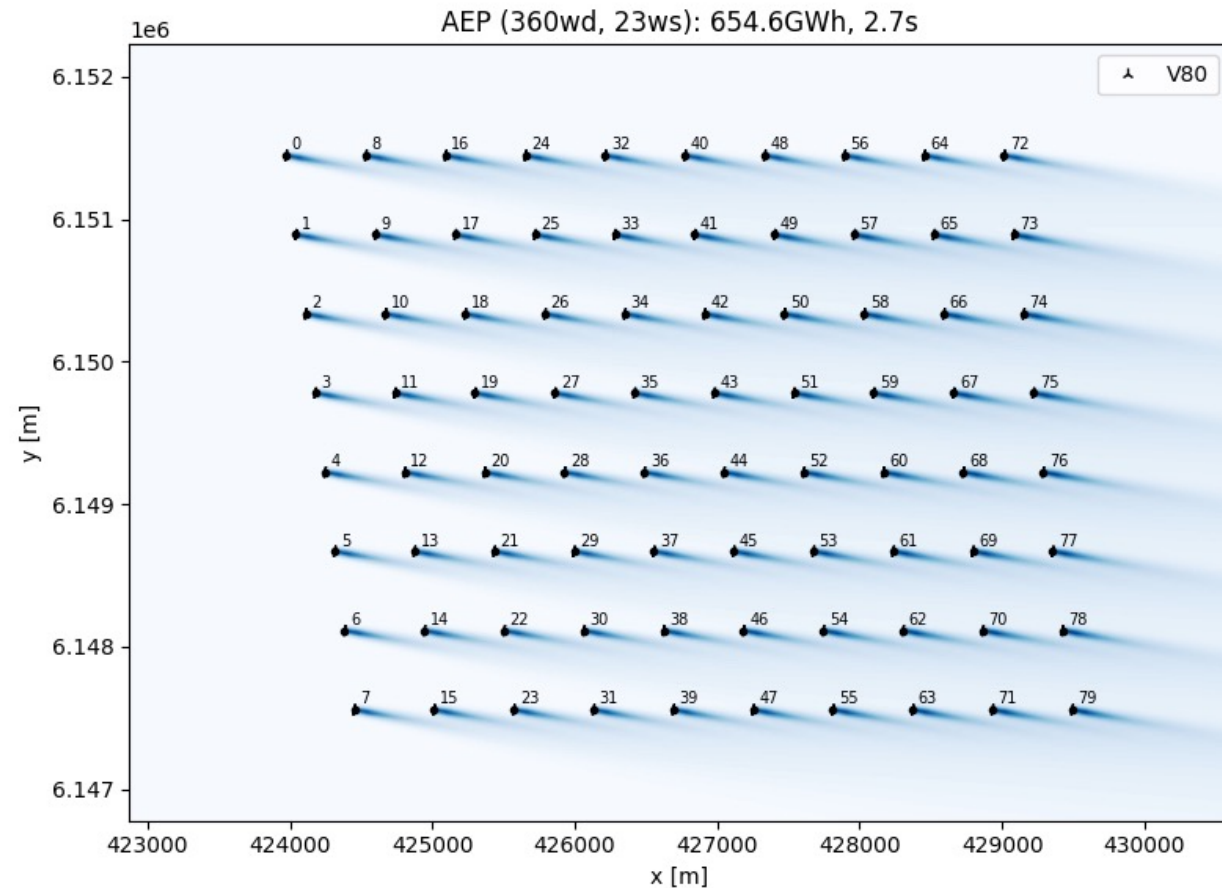
Mads M. Pedersen

From PyWake to Dynamiks

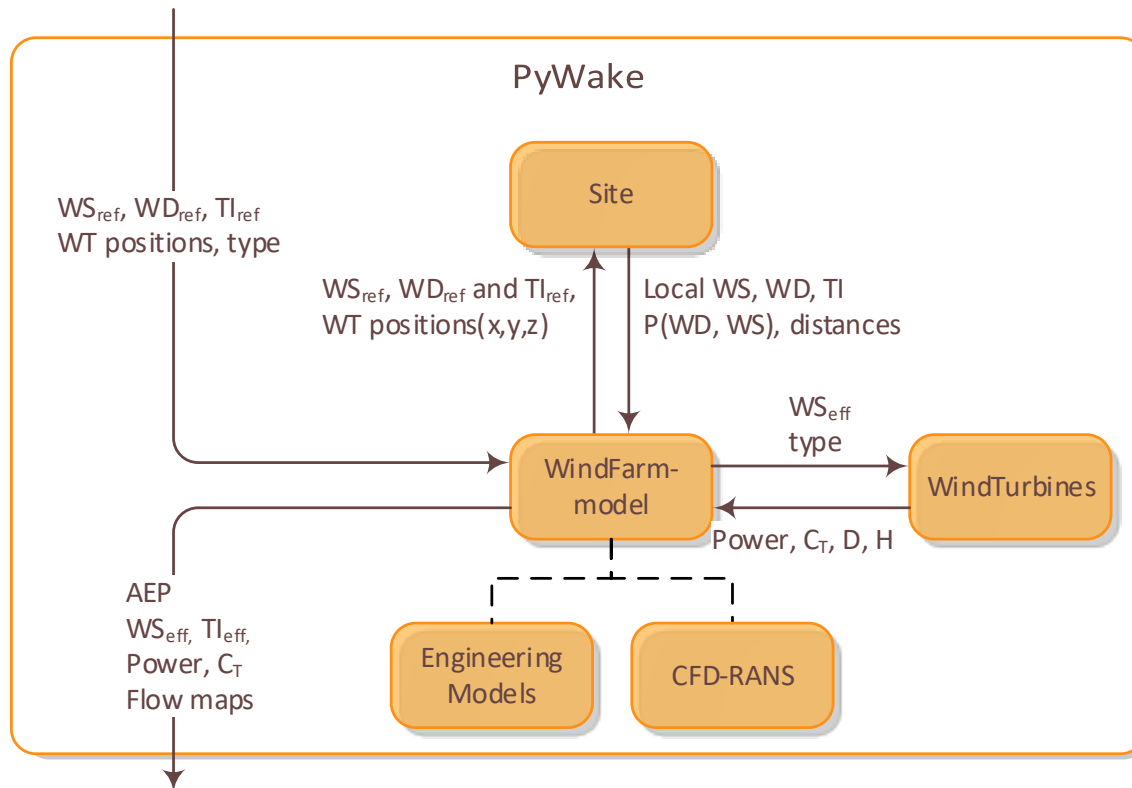


PyWake

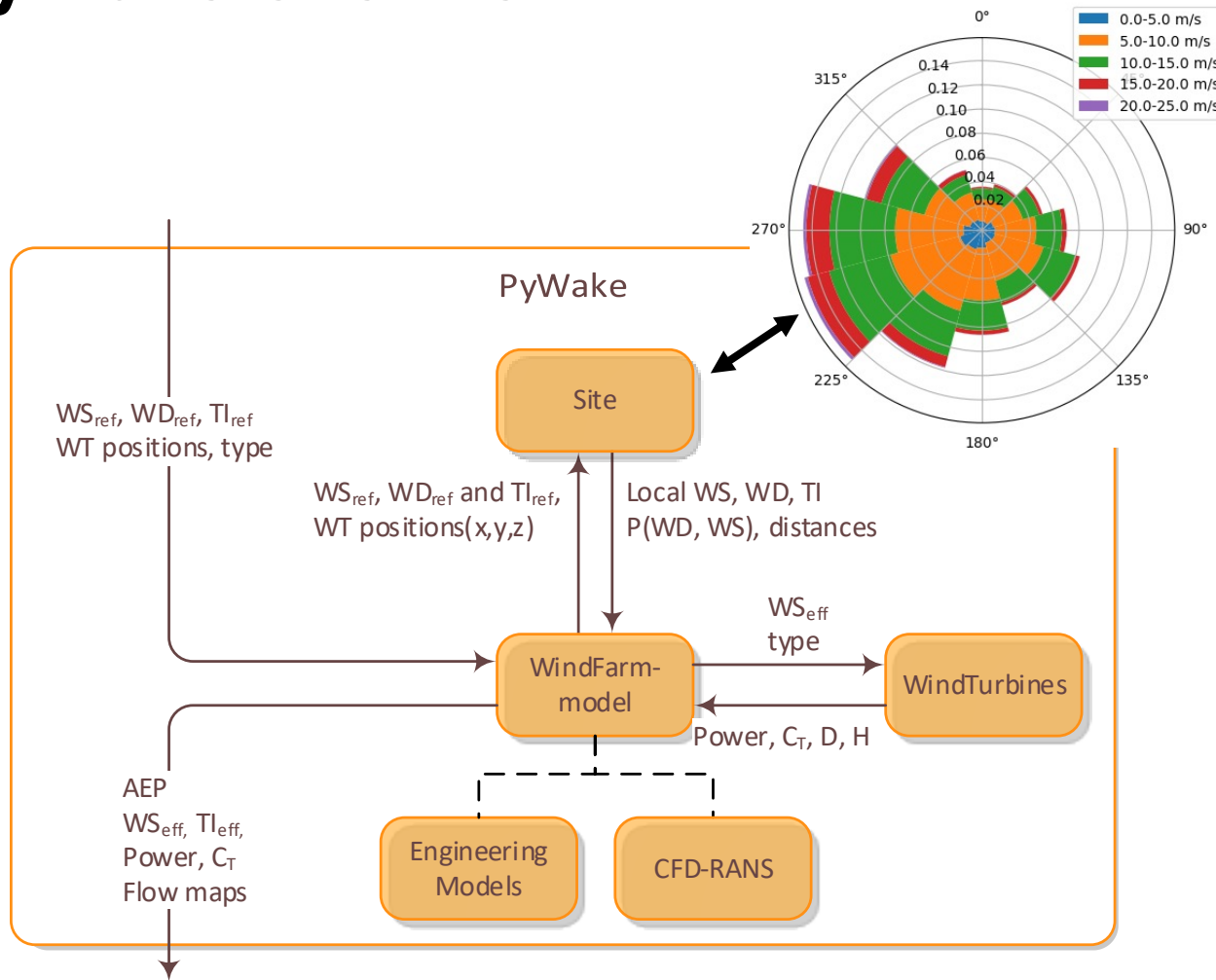
- Open source python package from DTU
- Static wind farm simulator
- Computes:
 - Effective wind speed (including wakes)
 - Power, AEP
 - Flow maps
 - Analytical gradients via automatic differentiation
- Very fast
- Suitable for optimization



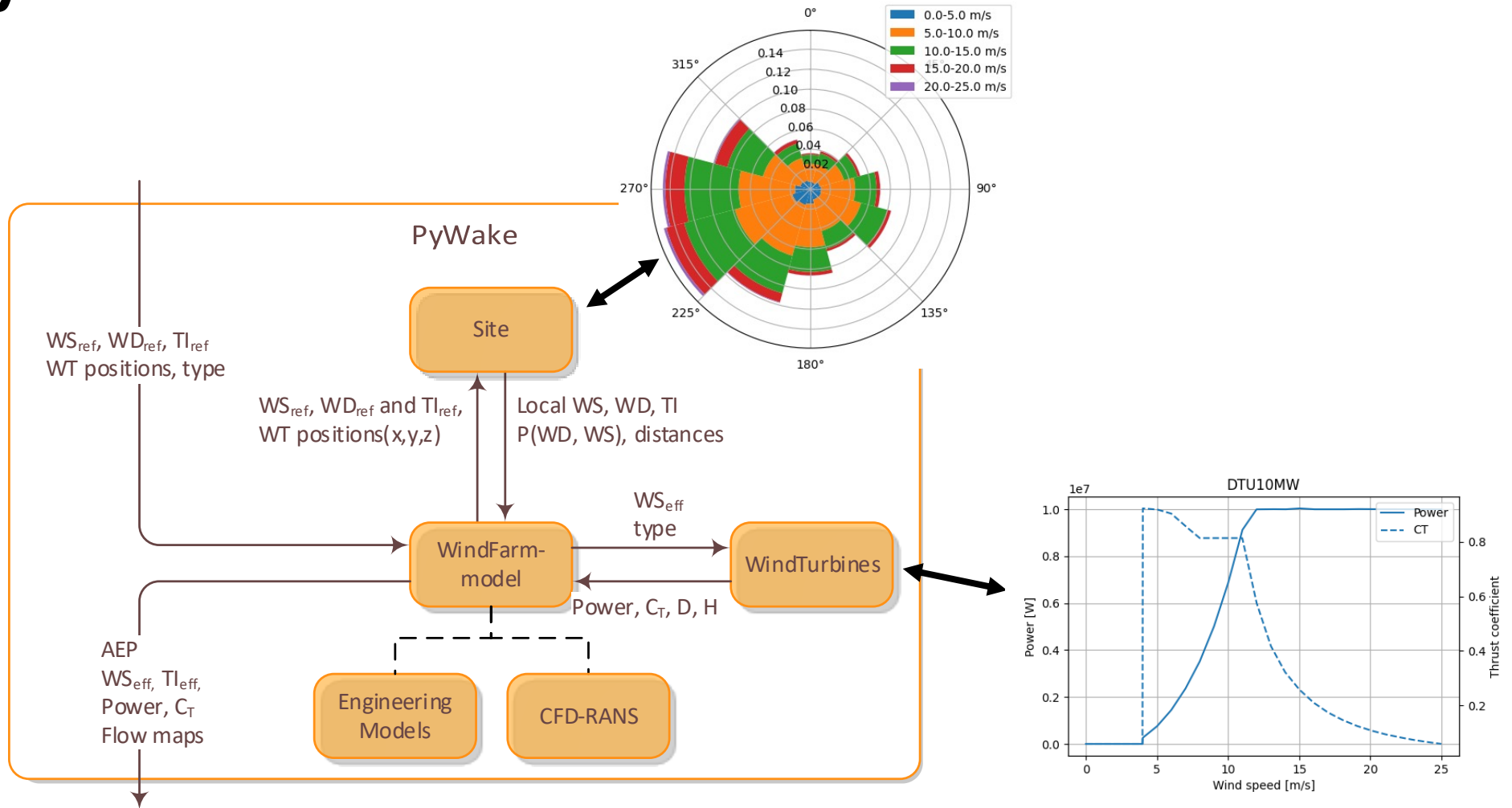
PyWake overview



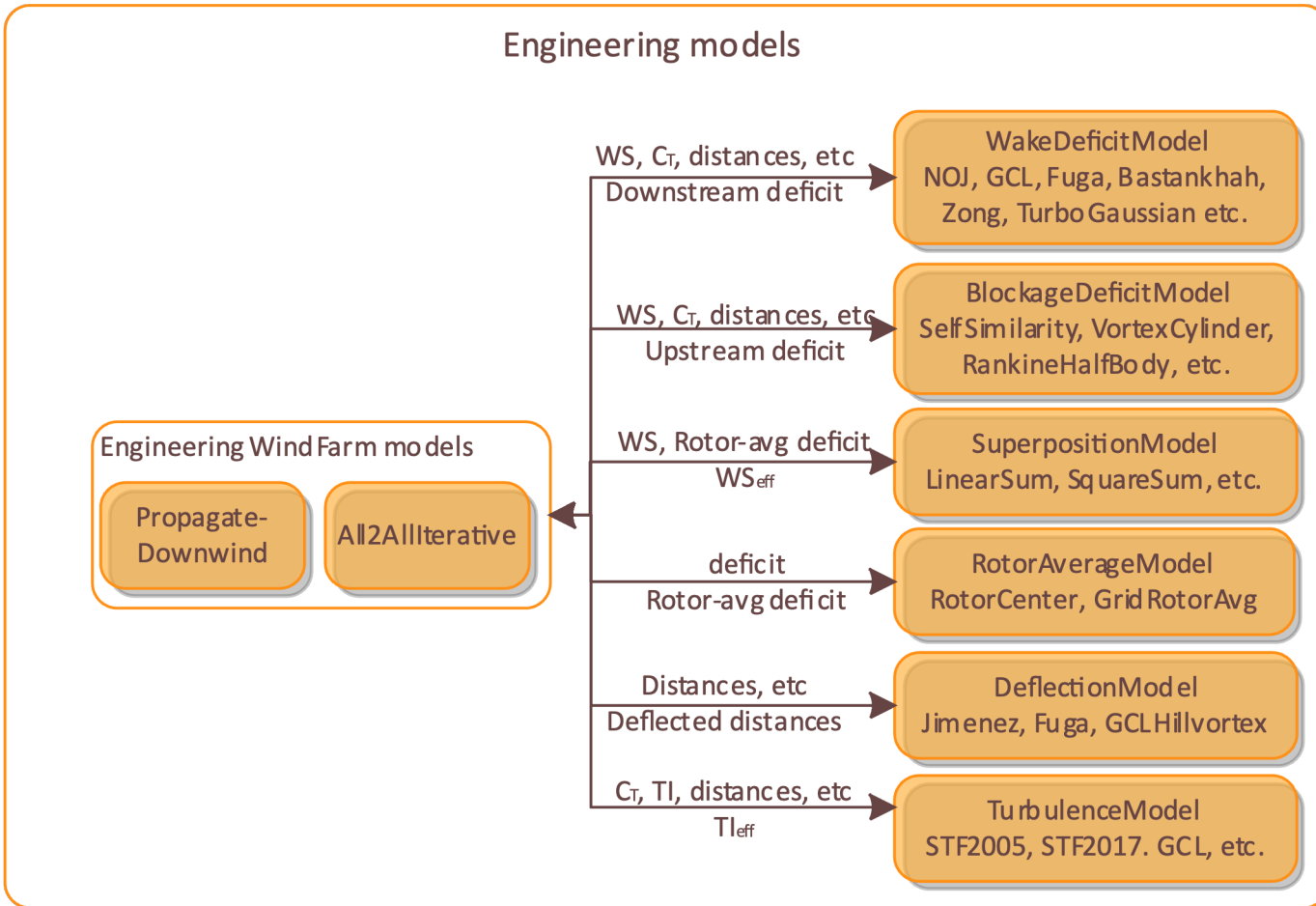
PyWake overview



PyWake overview

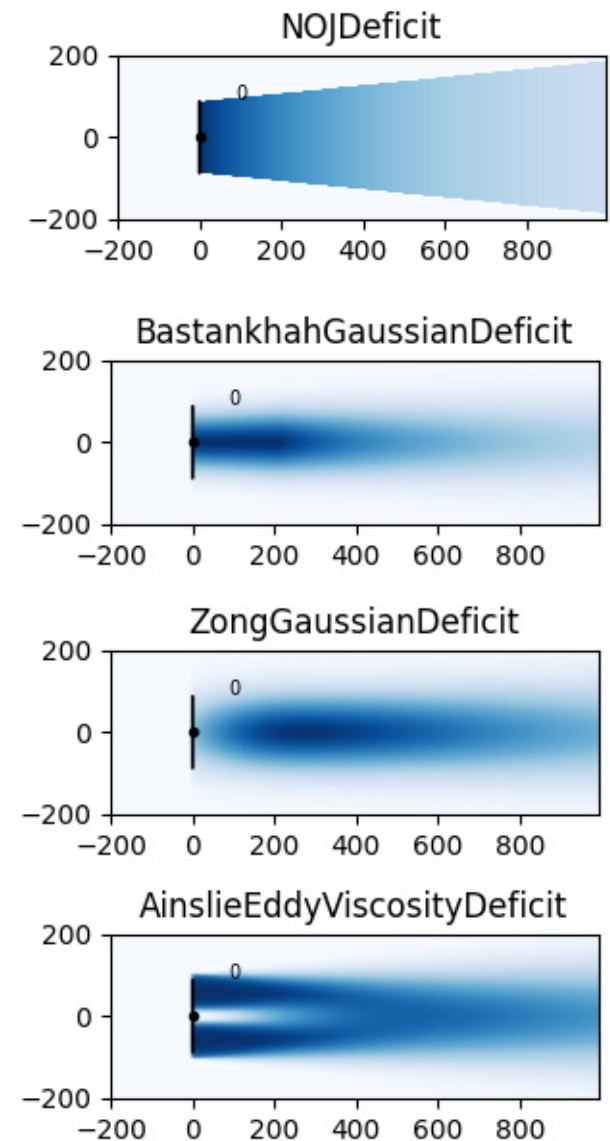
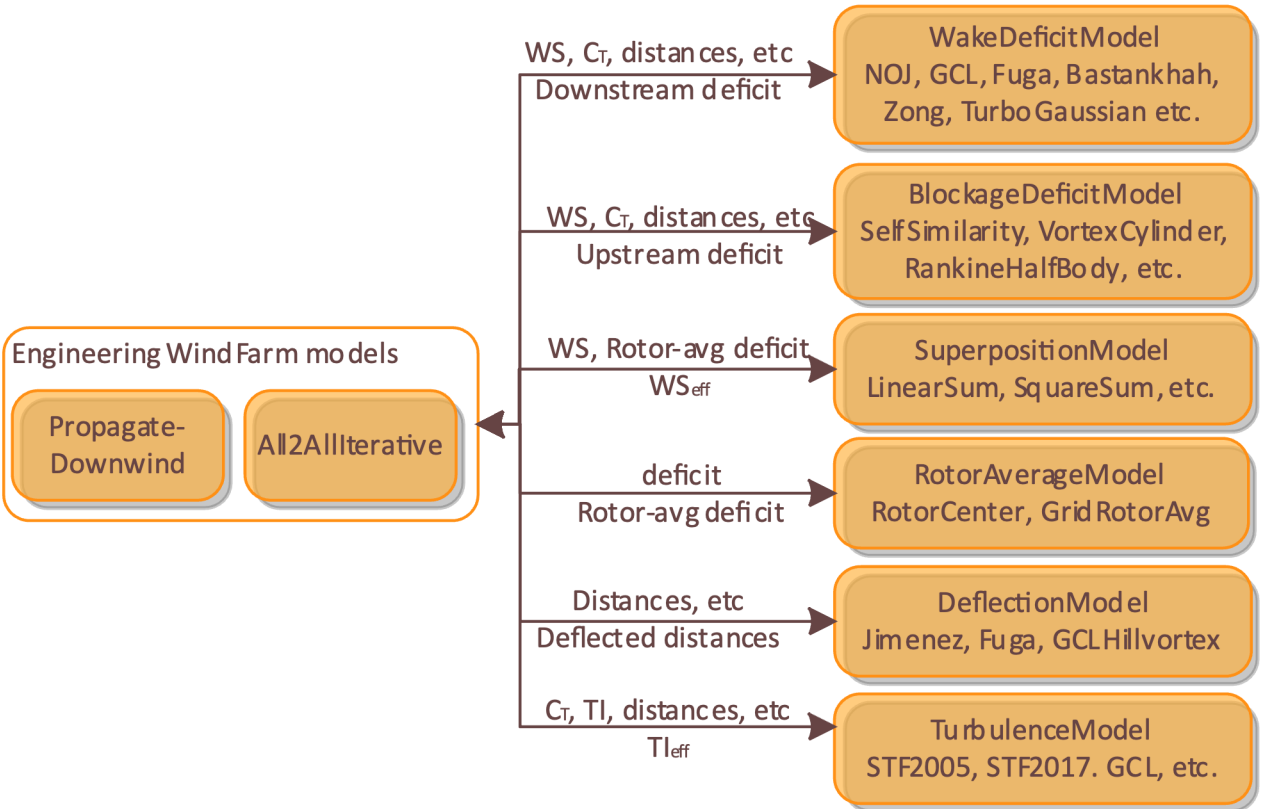


PyWake engineering models



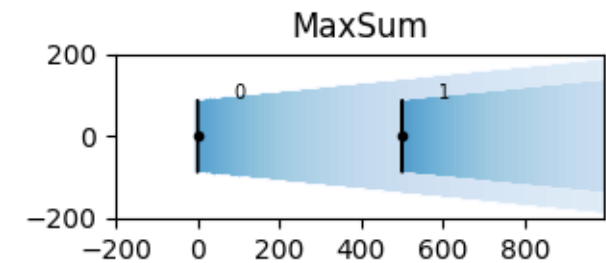
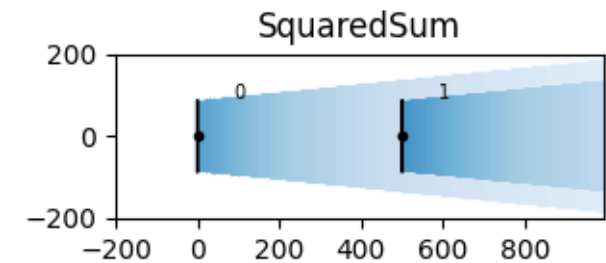
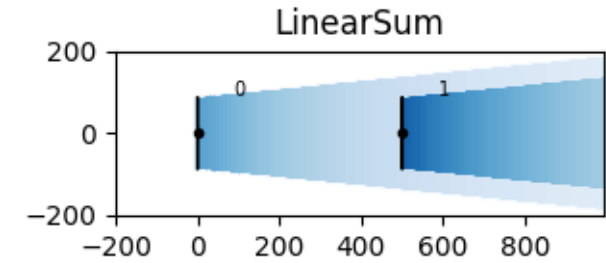
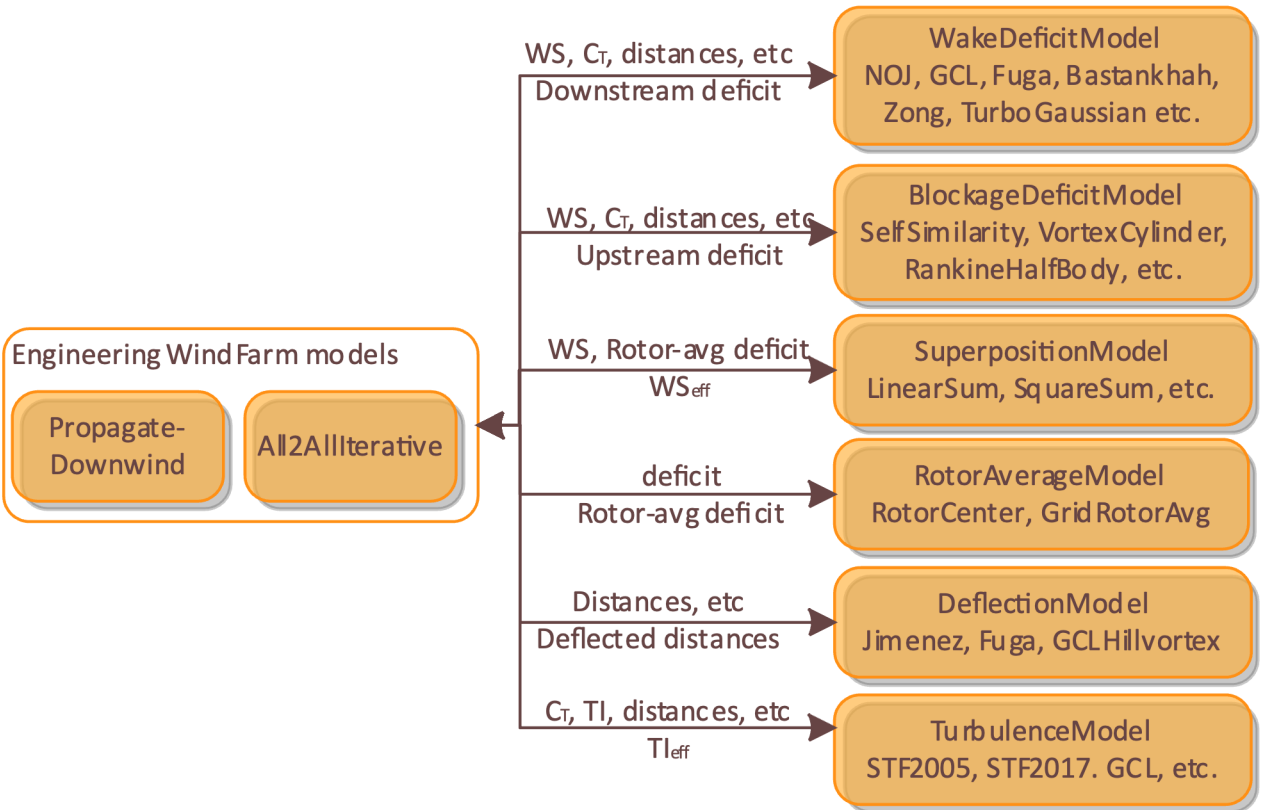
PyWake wake deficit models

Engineering models

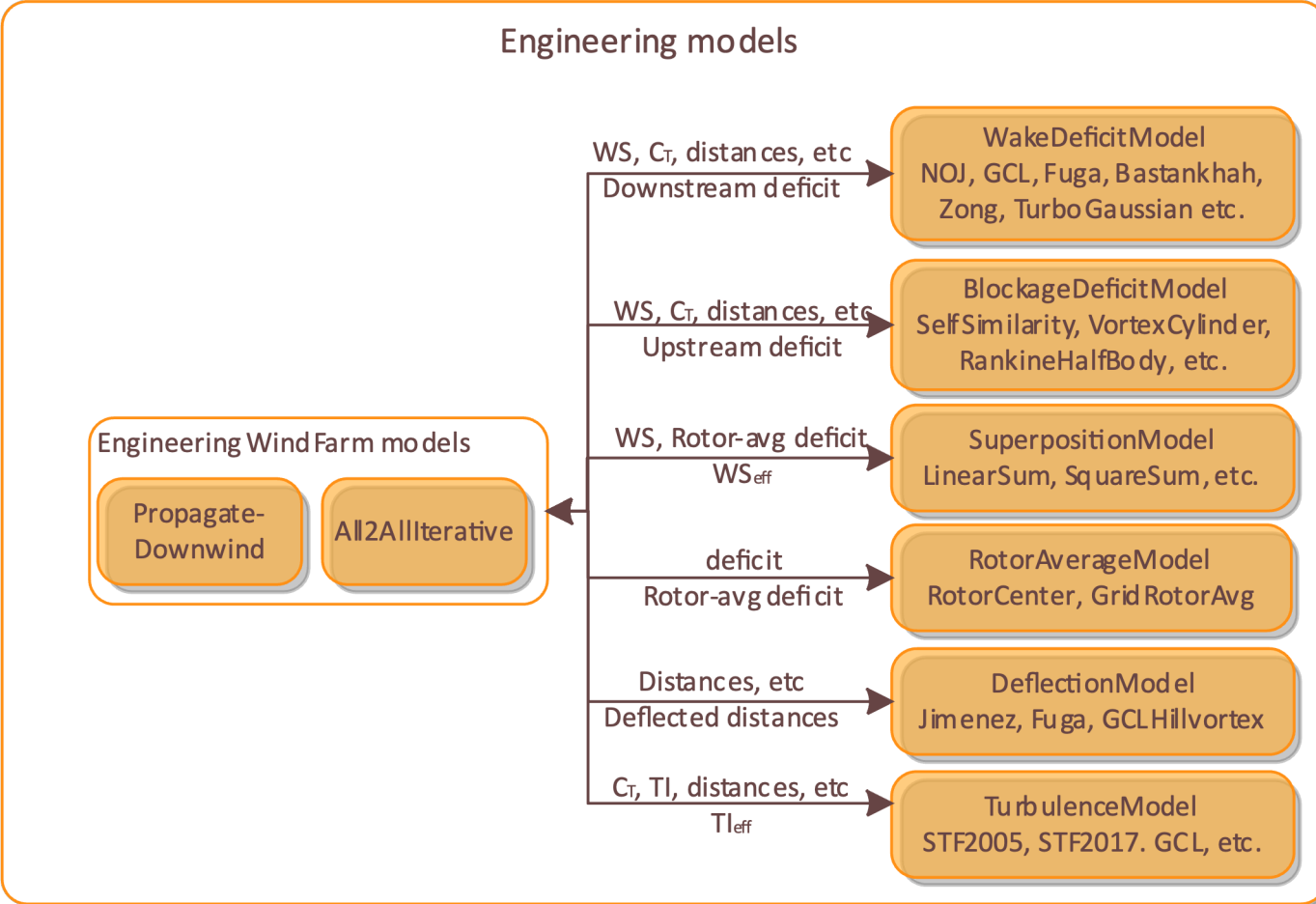


PyWake wake deficit models

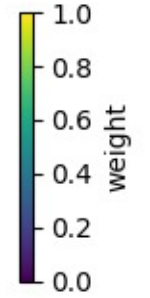
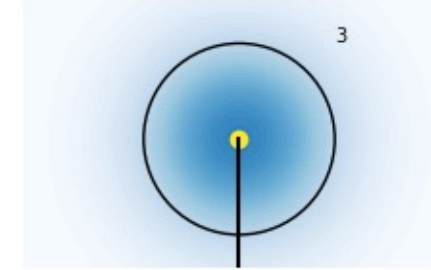
Engineering models



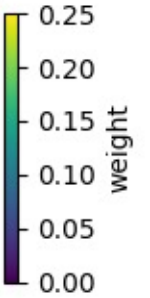
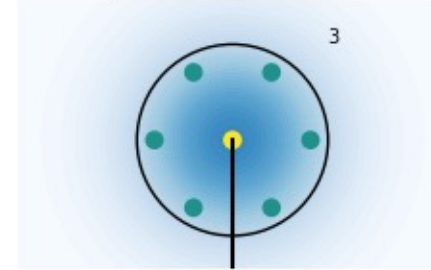
PyWake wake deficit models



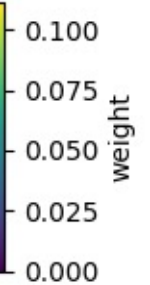
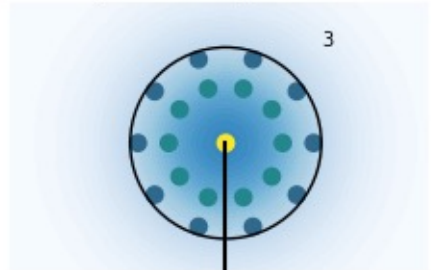
RotorCenter, avg deficit: 4.25m/s



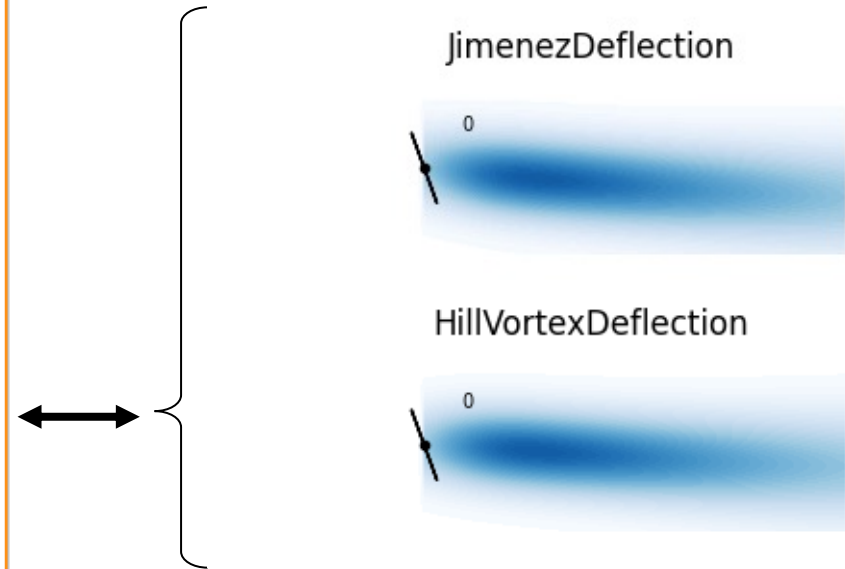
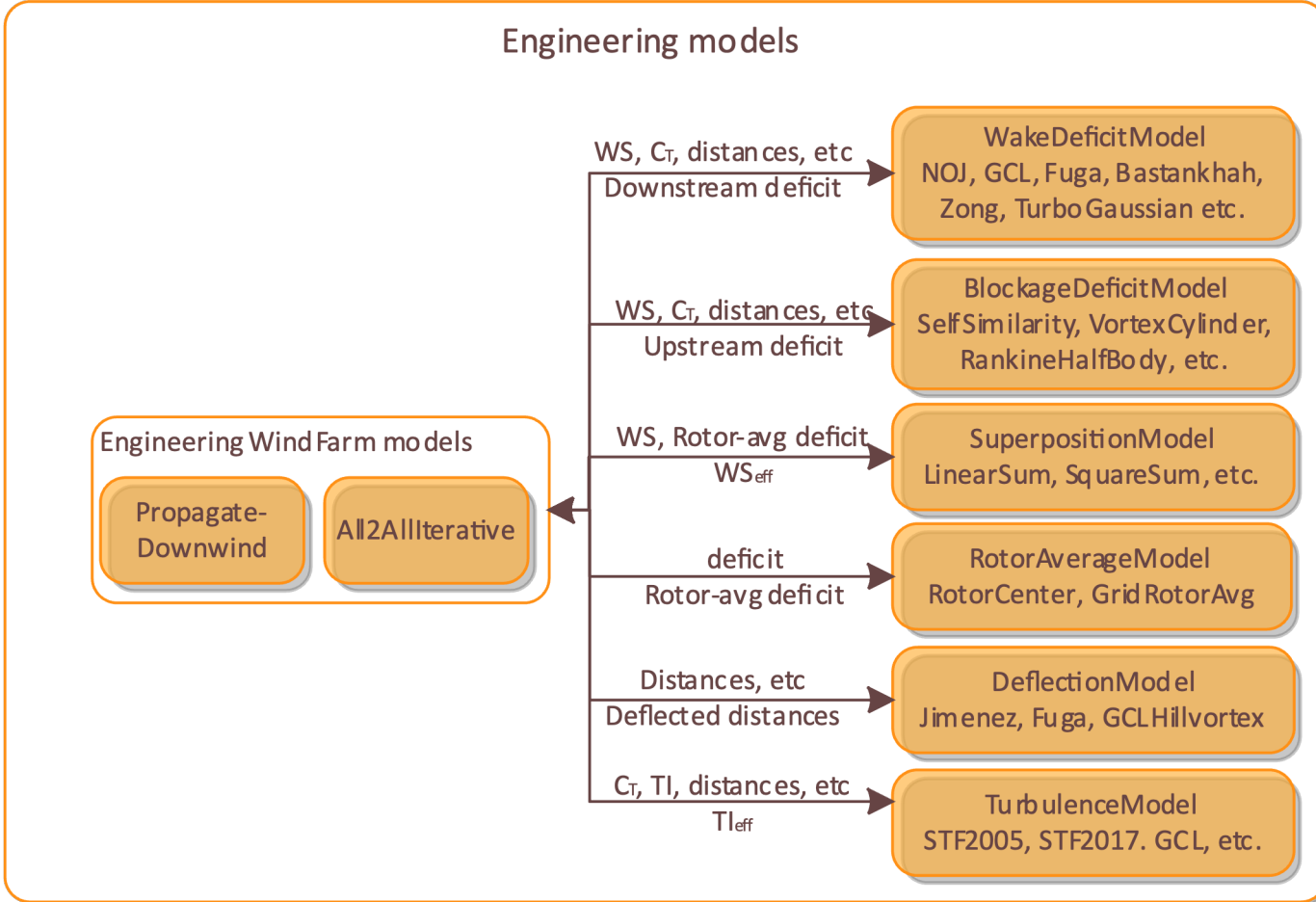
CGIRotorAvg(7), avg deficit: 2.92m/s



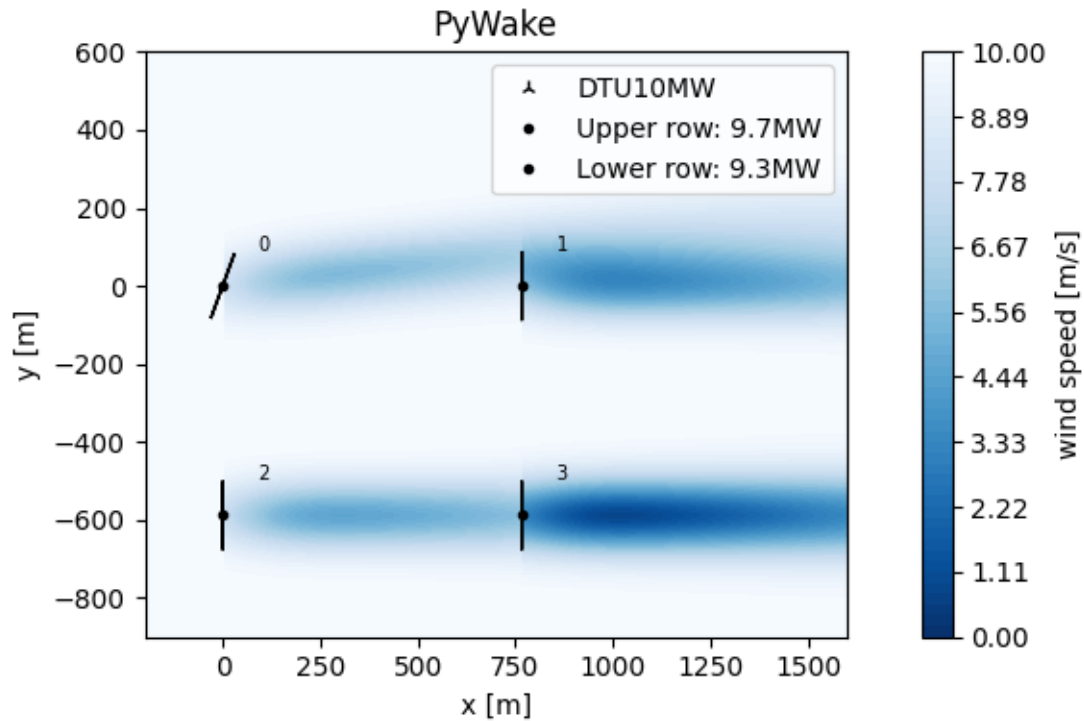
CGIRotorAvg(21), avg deficit: 2.92m/s



PyWake wake deficit models

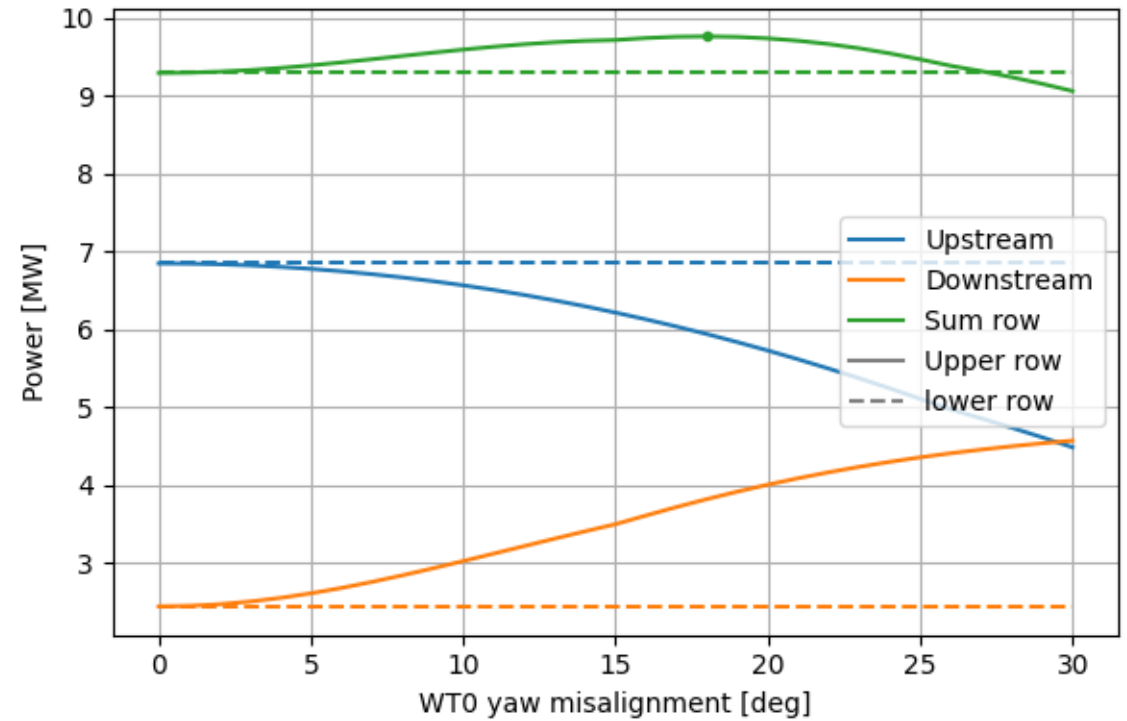
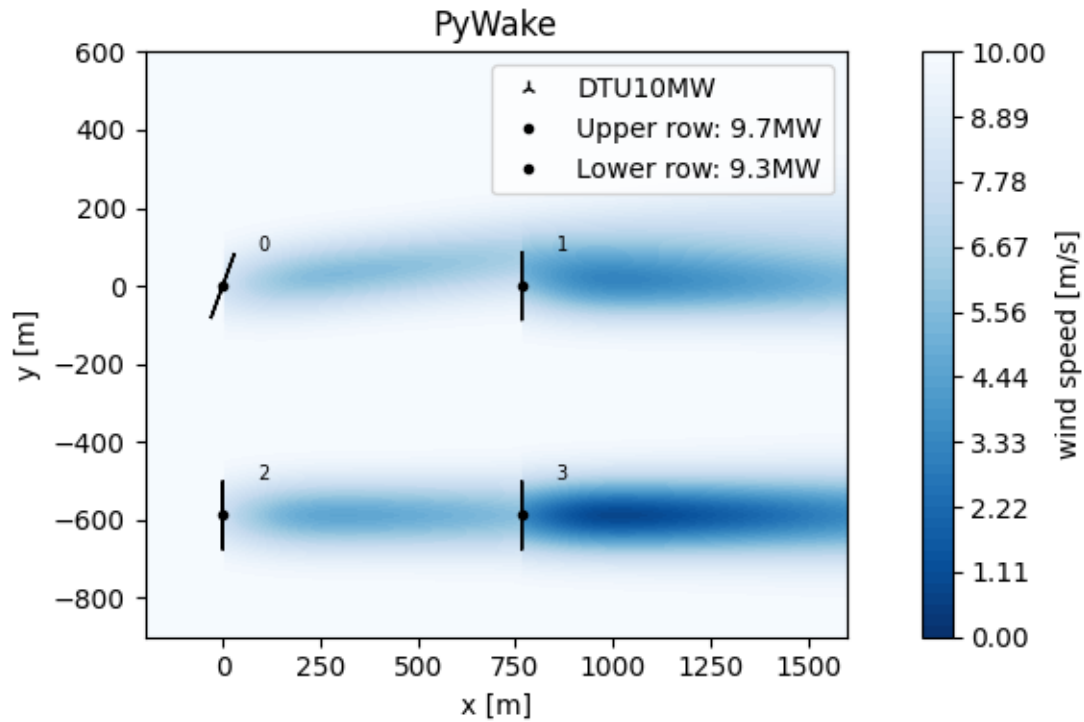


Case study

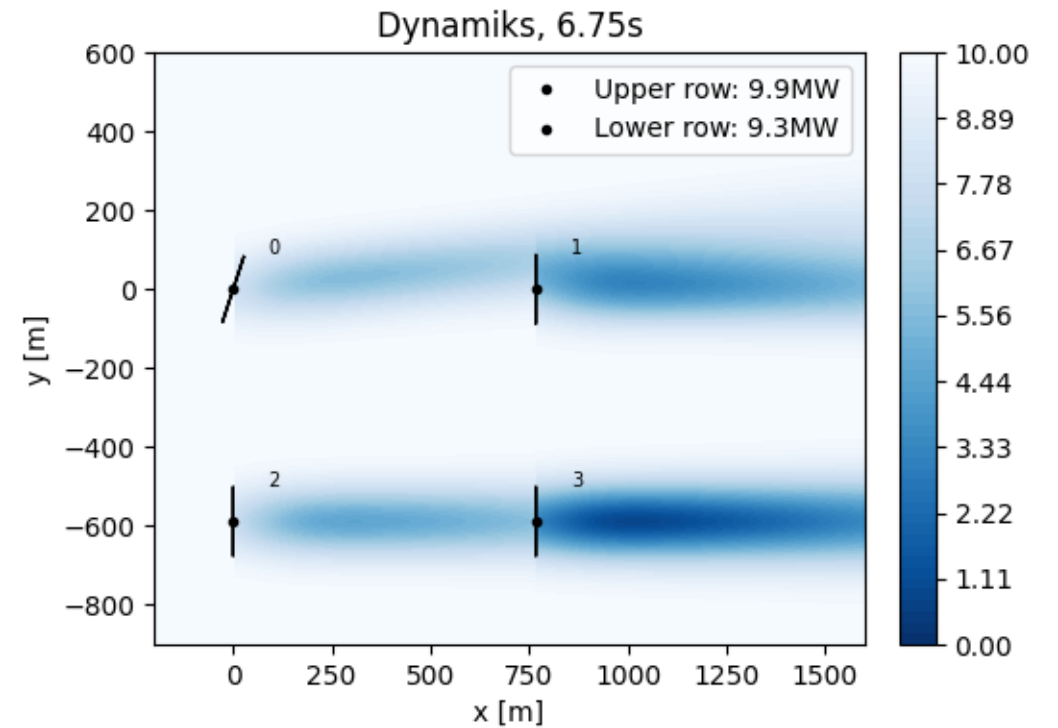
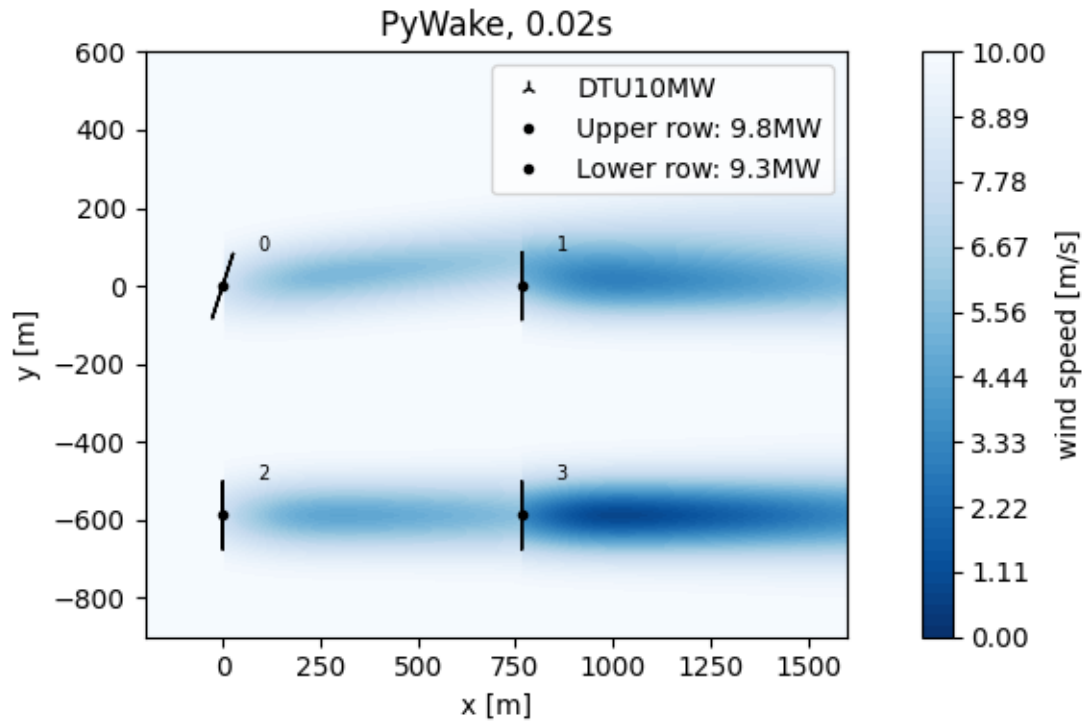


- 2x2 DTU 10 MW wind turbines
 - $Power = power(\cos \theta_{yaw} \cdot ws)$
 - $CT = ct(\cos \theta_{yaw} \cdot ws) \cos^2 \theta_{yaw}$
- 10m/s, 6% turbulence intensity
- Zong gaussian wake deficit
- Linear superposition
- 7 points rotor average
- Jimenez wake deflection ($\beta = 0.0268 \sim 6\%$ TI)

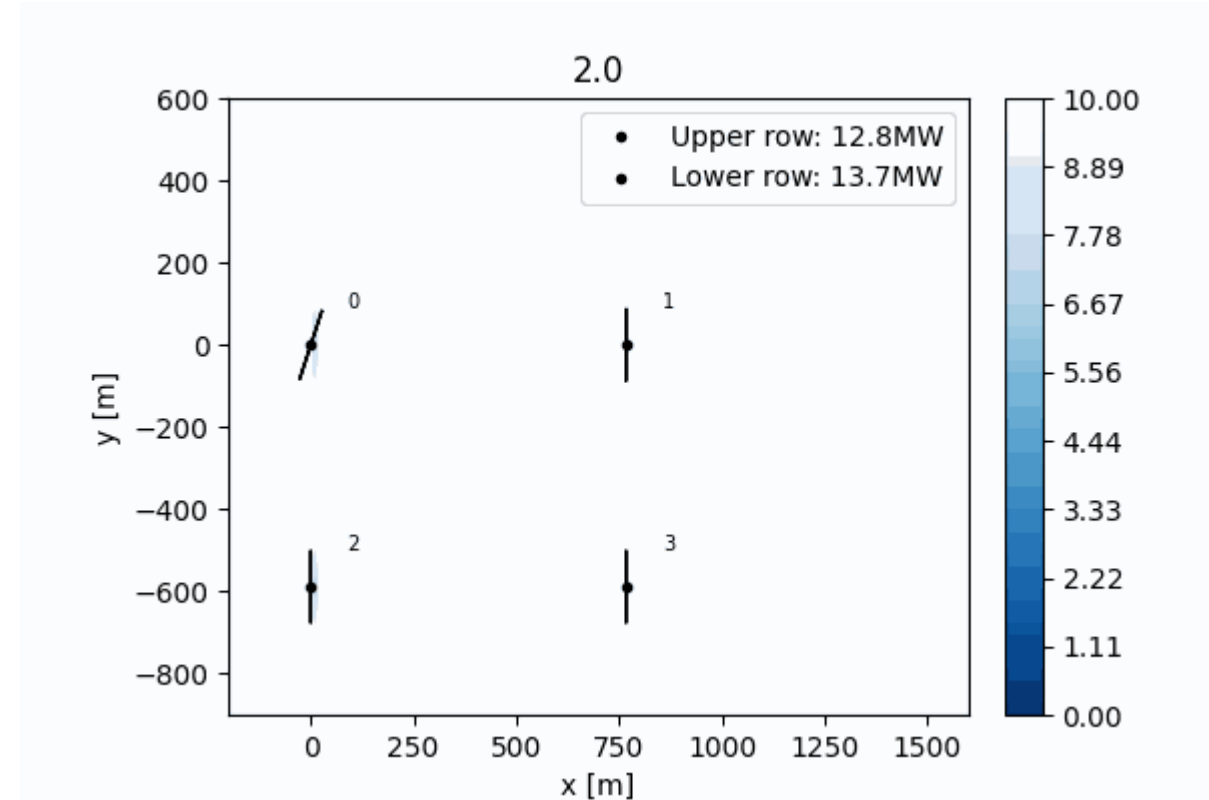
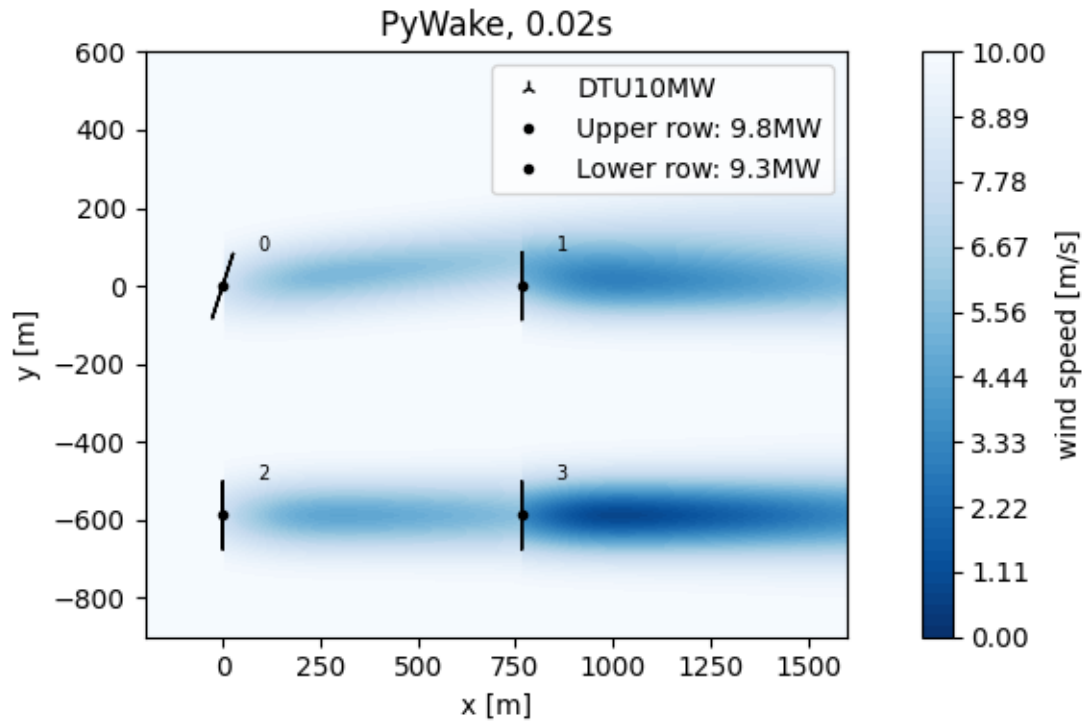
PyWake to Dynamiks



PyWake to Dynamiks



PyWake to Dynamiks



Dynamiks

Dynamiks: Dynamic wind system simulator

Time series

Single blade to
multiple wind farms

Inflow, wind turbines,
wakes

- Open source python framework from DTU
 - Interfaces HAWC2, EllipSys3D (commercial software, requires licenses)
- User friendly and easy to install
- Modular, flexible and multi fidelity

Dynamiks

Dynamiks: Dynamic wind system simulator

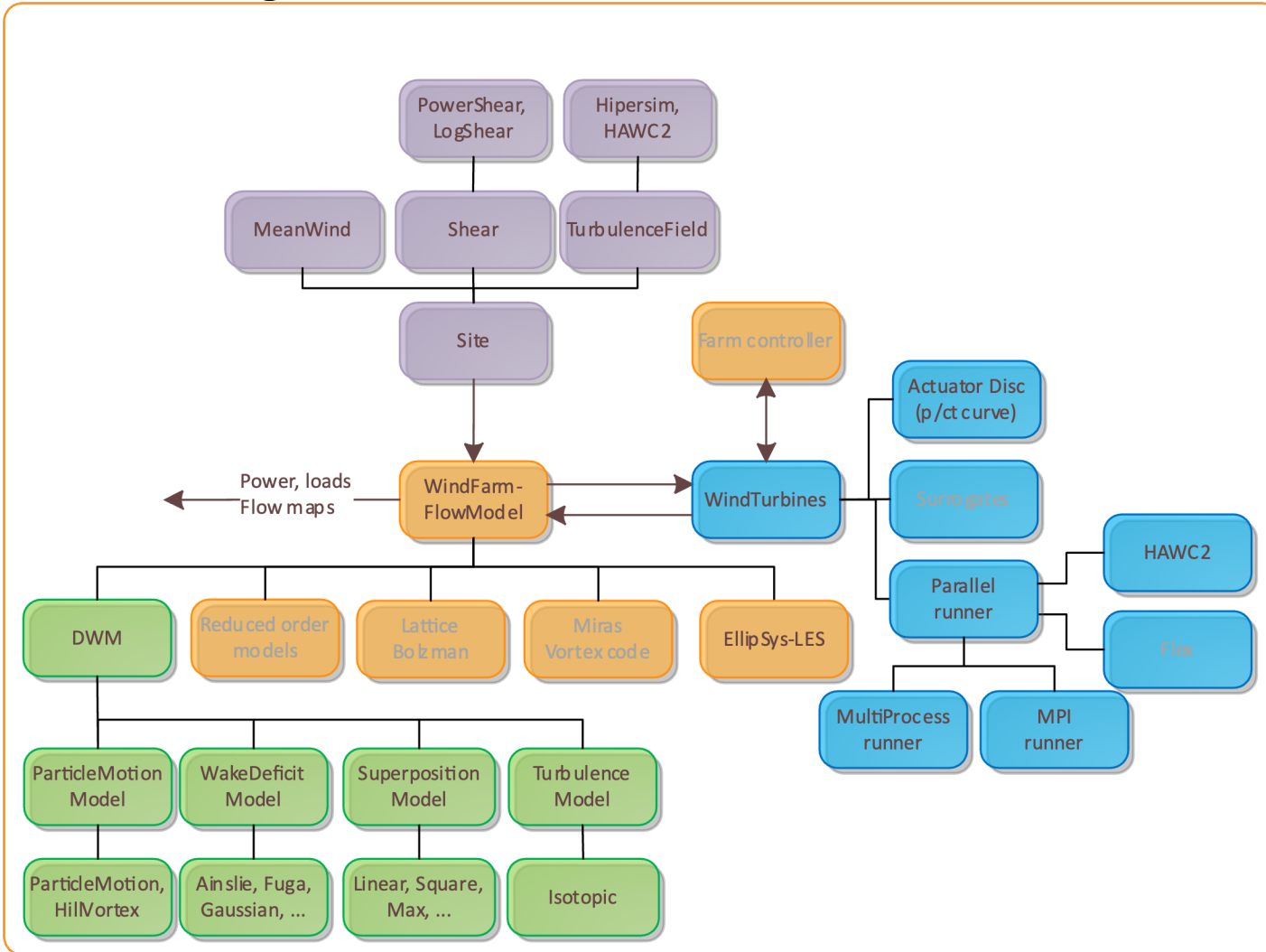
Time series

Single blade to
multiple wind farms

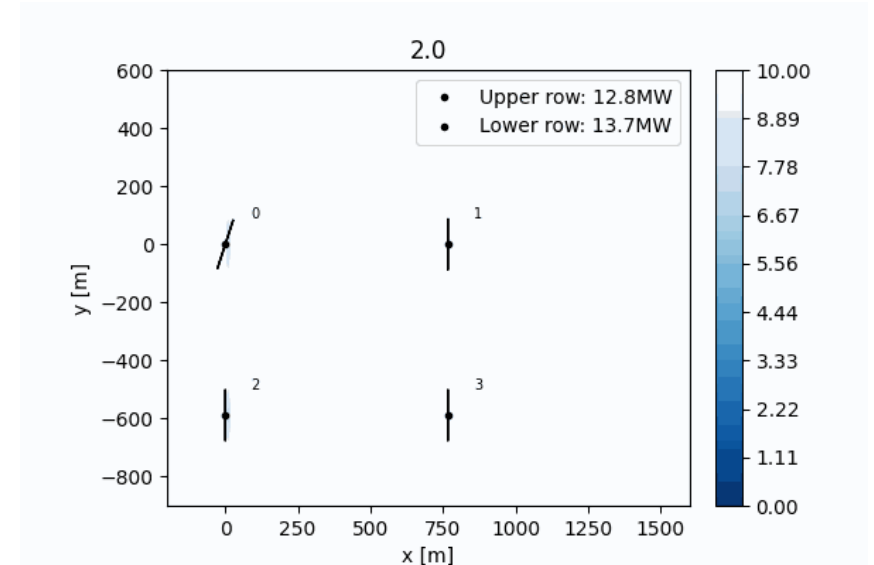
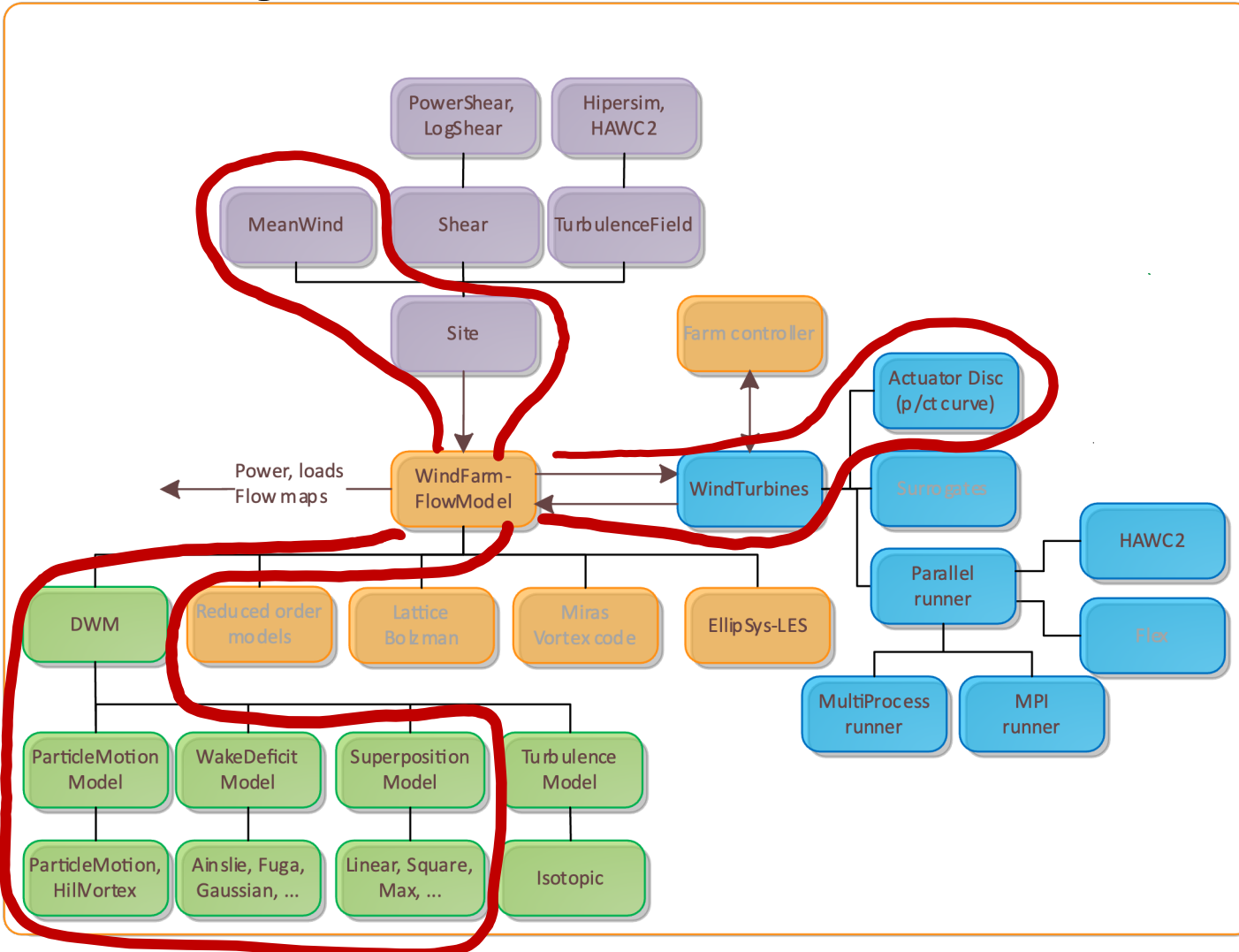
Inflow, wind turbines,
wakes

- Simulate
 - Extreme and fatigue loads of wind farms
 - Changing inflow (wind speed and direction)
 - Turbine control (start-up/shut-down, etc)
 - Wind farm control (derating, yaw to optimize total farm production)
- Validation of low-fidelity models against high-fidelity models

Dynamiks, modular, flexible and multifidelity



Dynamiks, modular, flexible and multifidelity



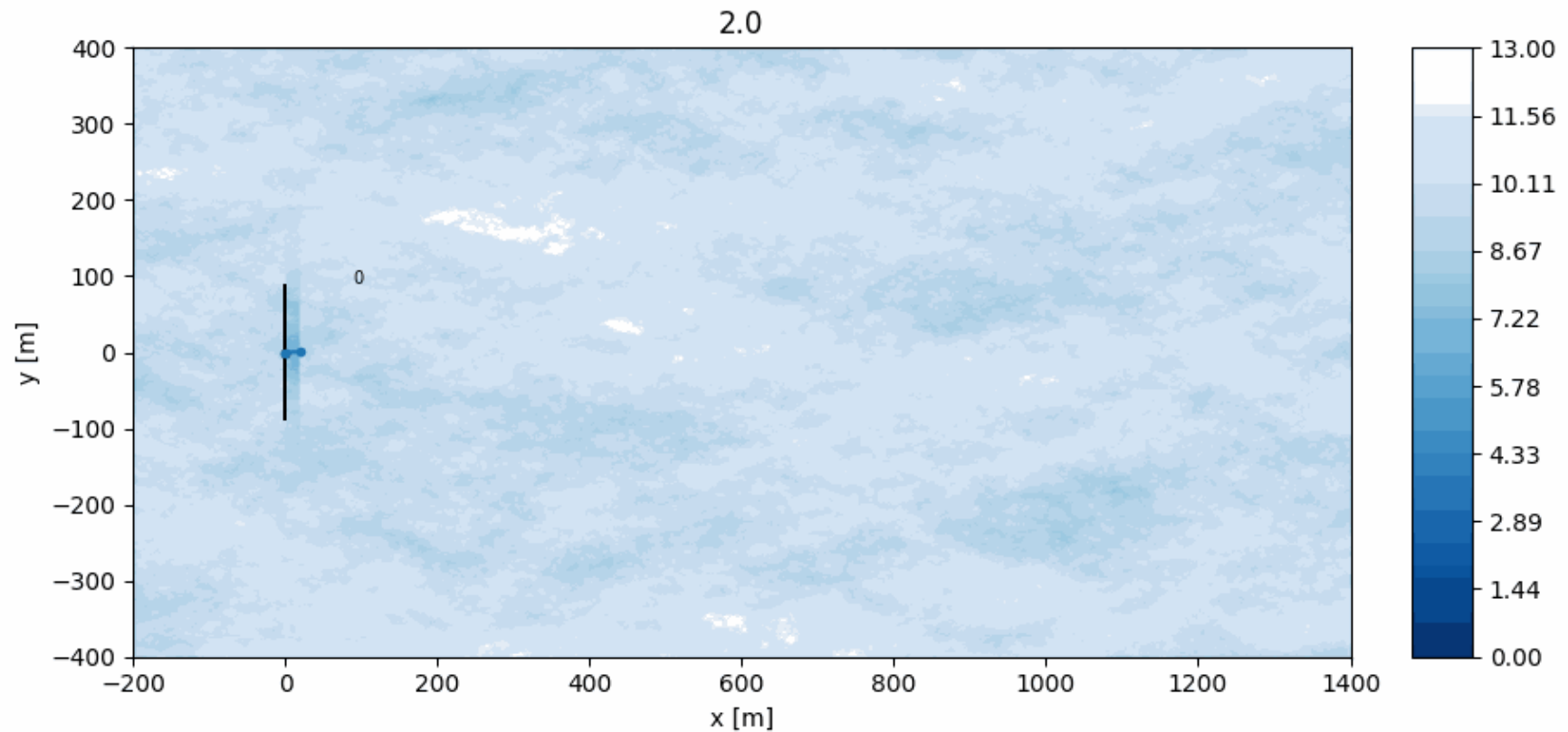
```

site = UniformSite(ws=10, ti=.06)
wts = PyWakeWindTurbines(x=wt_x, y=wt_y,
                          windTurbine=DTU10MW())
wts.yaw = [-18, 0, 0, 0]

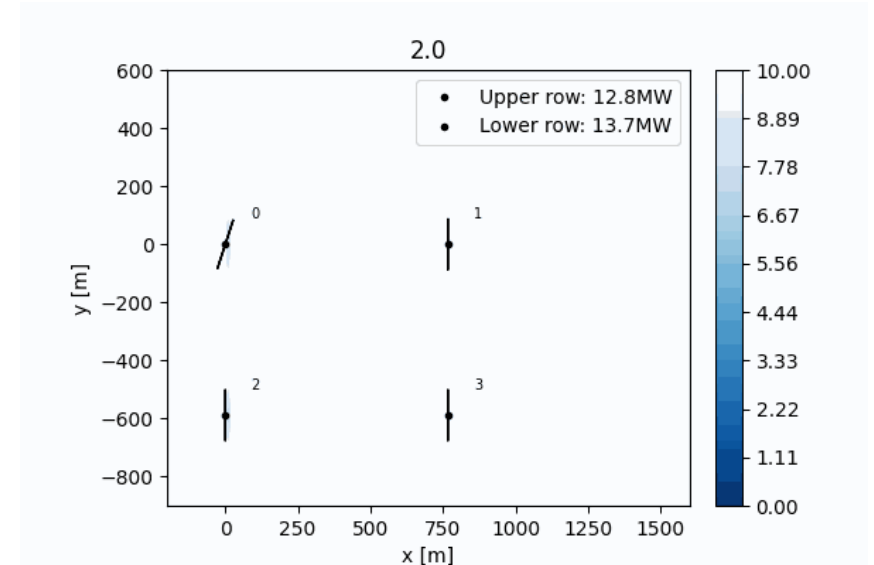
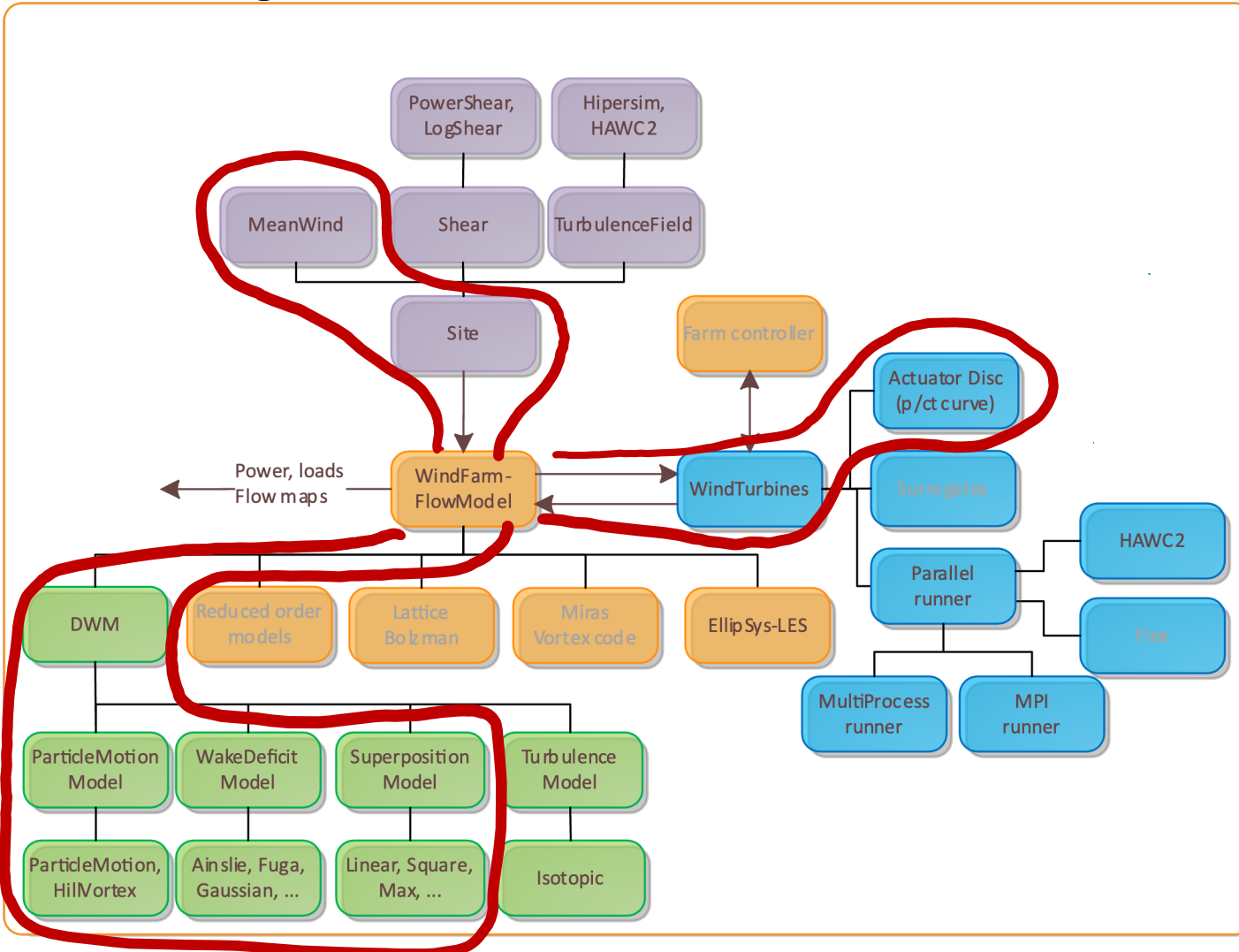
fs = DWMFlowSimulation(
    site=site,
    windTurbines=wts,
    ...)
fs.animate(250, view=...)

```

Dynamic Wake Meandering model (DWM)



Dynamiks, modular, flexible and multifidelity



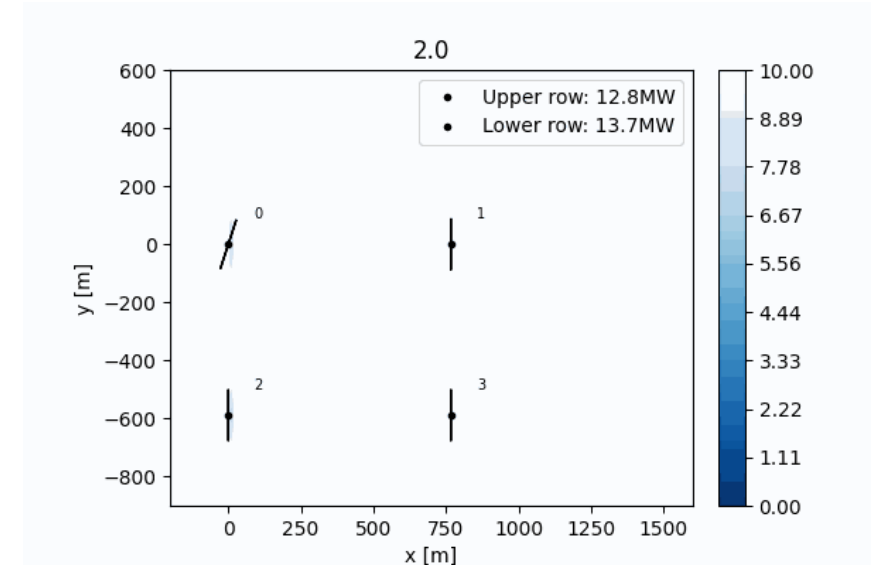
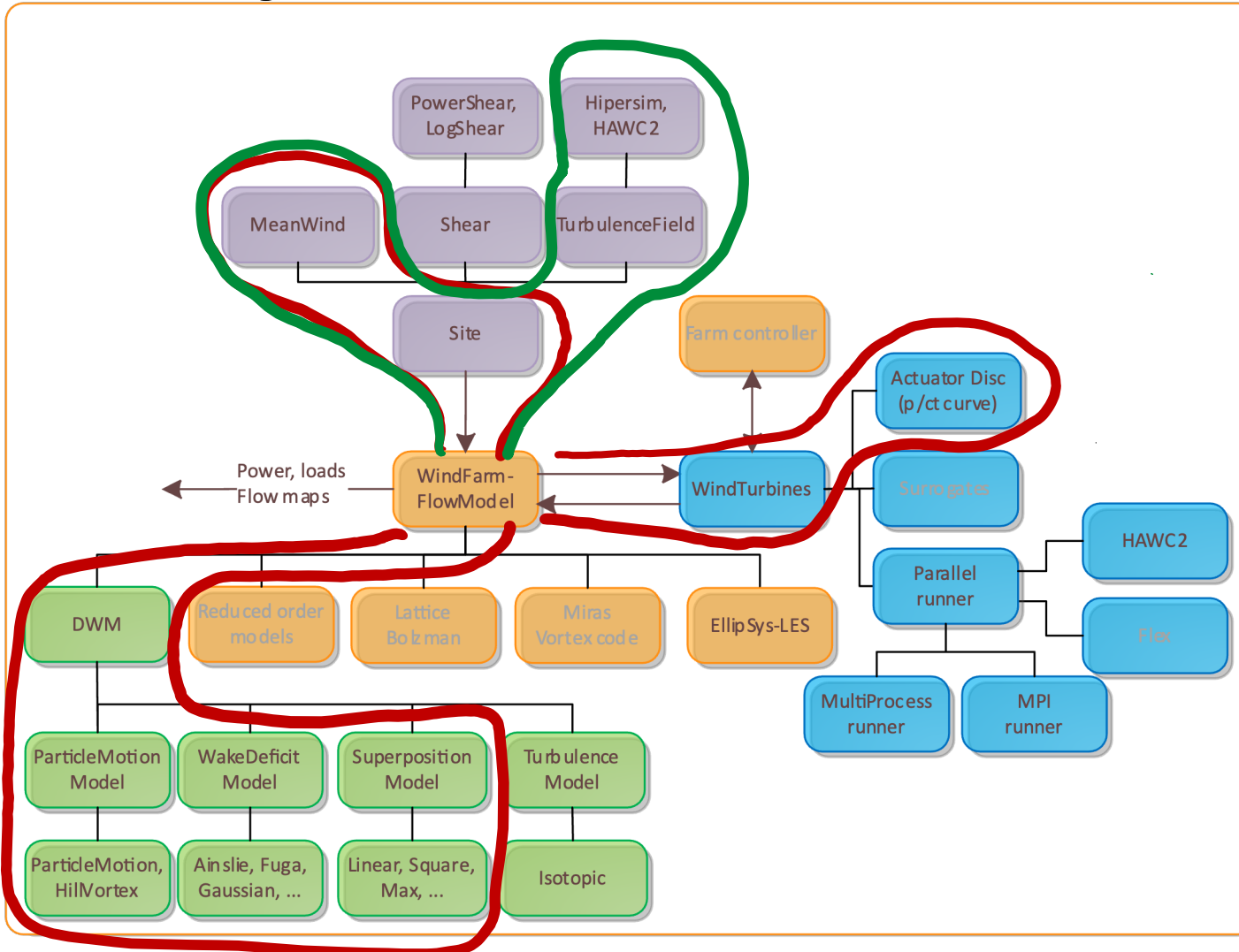
```

site = UniformSite(ws=10, ti=.06)
wts = PyWakeWindTurbines(x=wt_x, y=wt_y,
                        windTurbine=DTU10MW())
wts.yaw = [-18, 0, 0, 0]

fs = DWMFlowSimulation(
    site=site,
    windTurbines=wts,
    ...)
fs.animate(250, view=...)

```

Dynamiks, modular, flexible and multifidelity



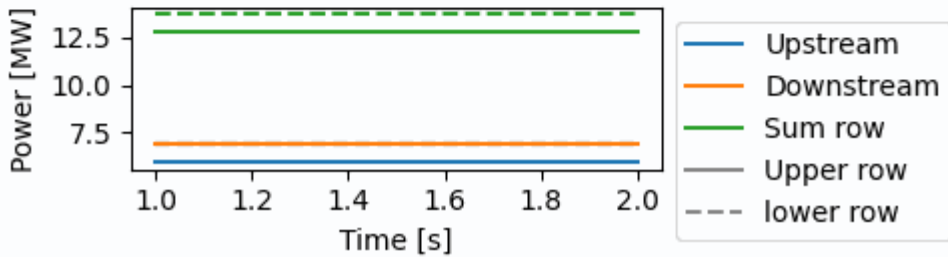
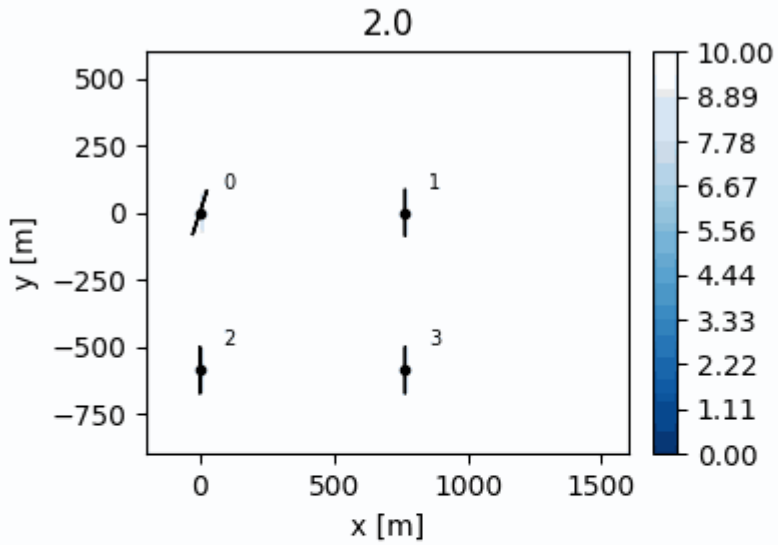
```

site = UniformSite(ws=10, ti=.06)
wts = PyWakeWindTurbines(x=wt_x, y=wt_y,
                        windTurbine=DTU10MW())
wts.yaw = [-18, 0, 0, 0]

fs = DWMFlowSimulation(
    site=site,
    windTurbines=wts,
    ...)
fs.animate(250, view=...)

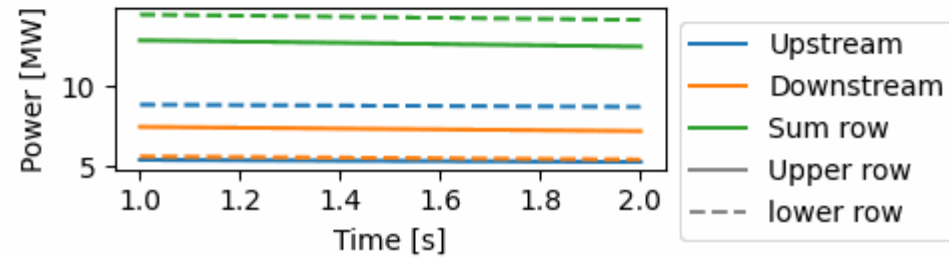
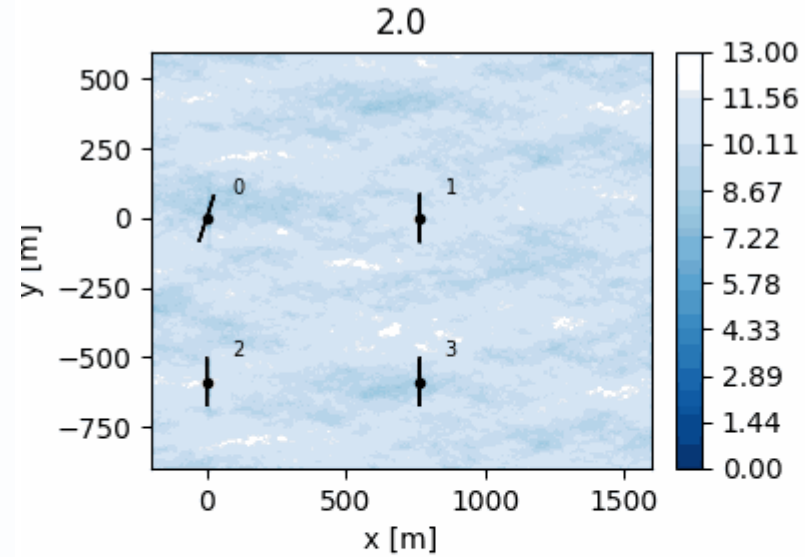
```

```
site = UniformSite(ws=10, ti=.06)
```

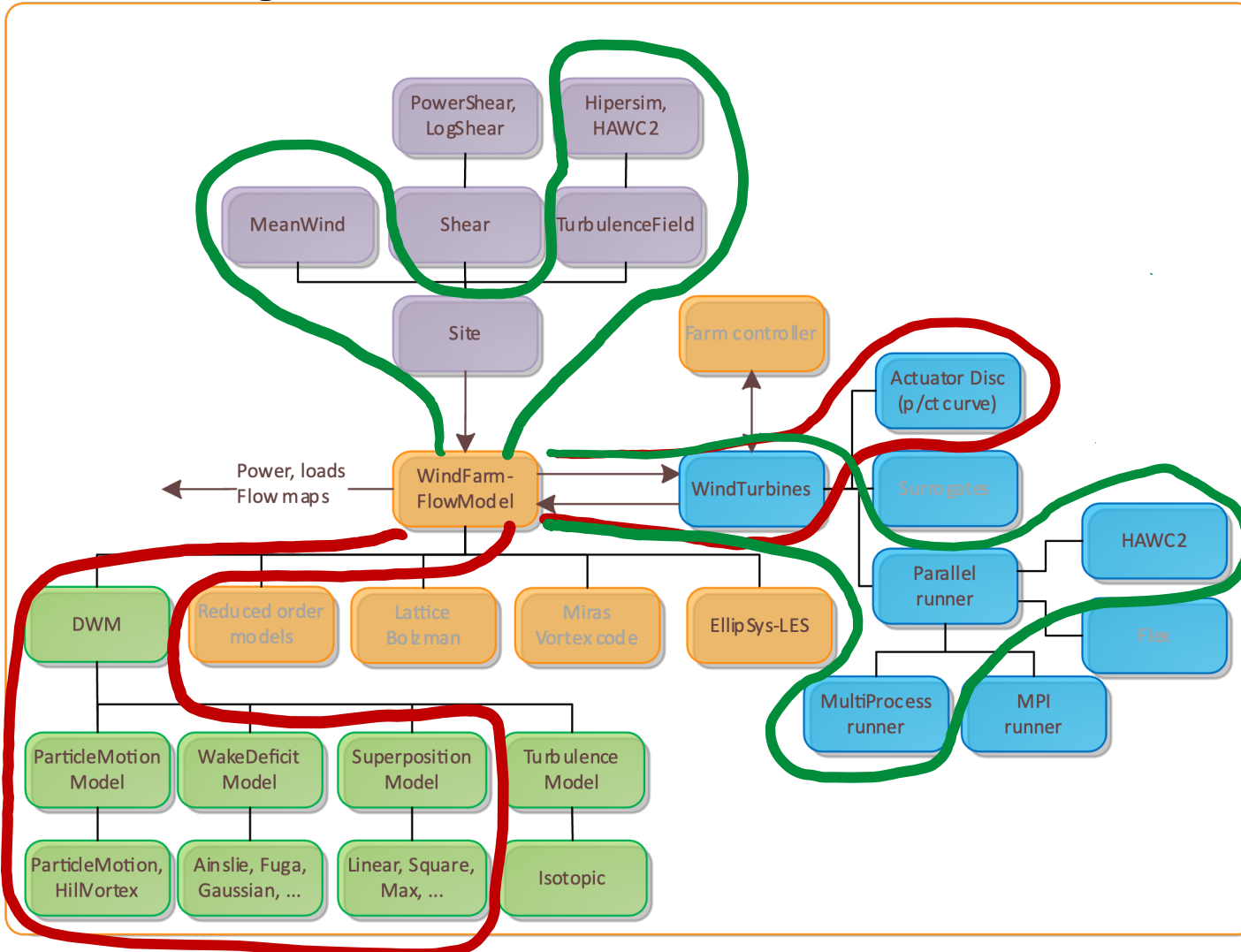


```
tf = MannTurbulenceField.generate(Nxyz, dxyz)
tf.scale_TI(TI=.06, U=10)
```

```
site = TurbulenceFieldSite(ws=10, turbulenceField=tf)
```

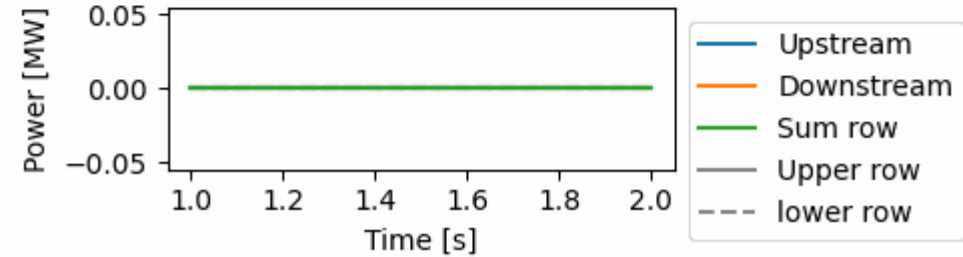
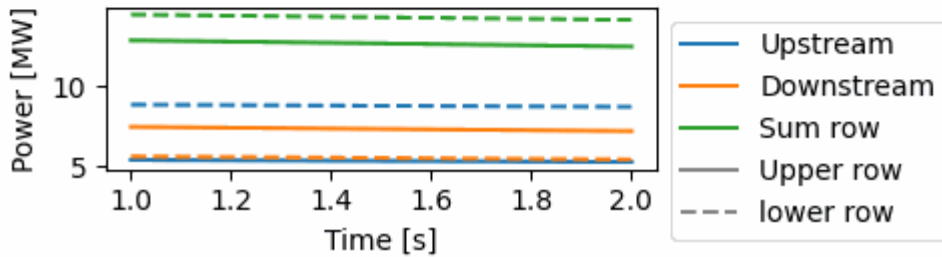
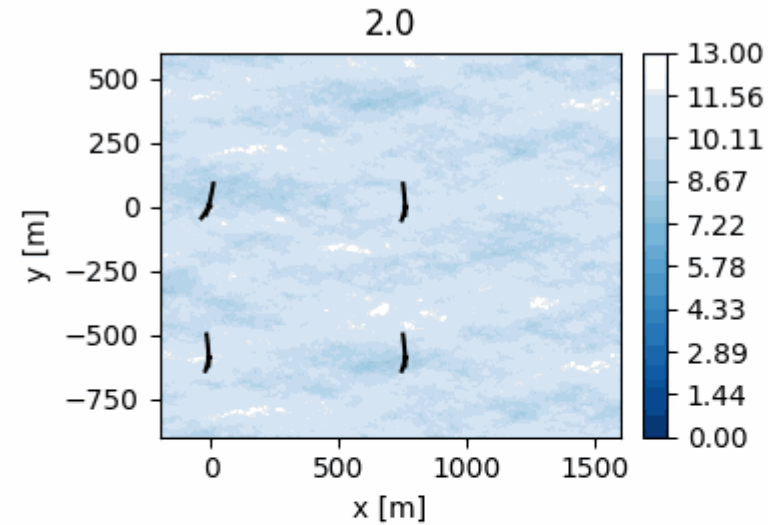
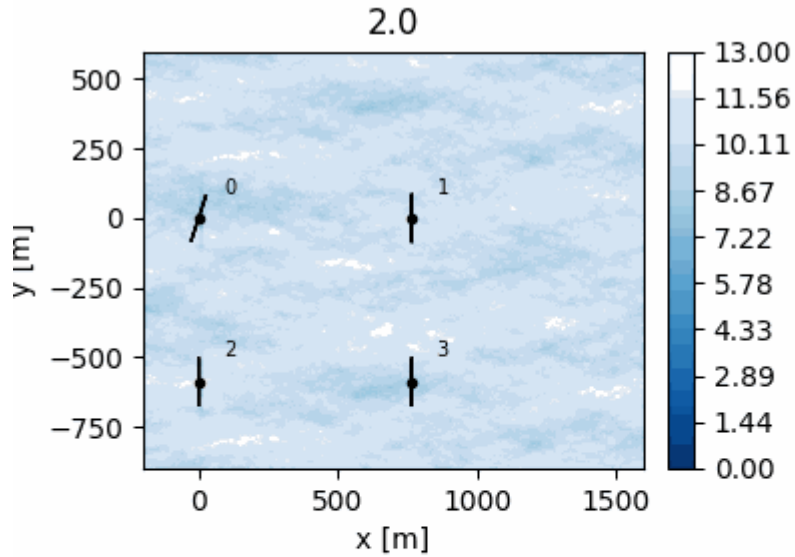


Dynamiks, modular, flexible and multifidelity




```
wts = PyWakeWindTurbines(
    x=wt_x, y=wt_y,
    windTurbine=DTU10MW())
wts.yaw = [-18,0,0,0]
```

```
wts = HAWC2WindTurbines(
    x=wt_x, y=wt_y,
    htc_filename_lst=['htc/DTU_10MW_RWT_yaw-18.htc',
                    'htc/DTU_10MW_RWT.htc'],
    types=[0,1,1,1])
```



HAWC2

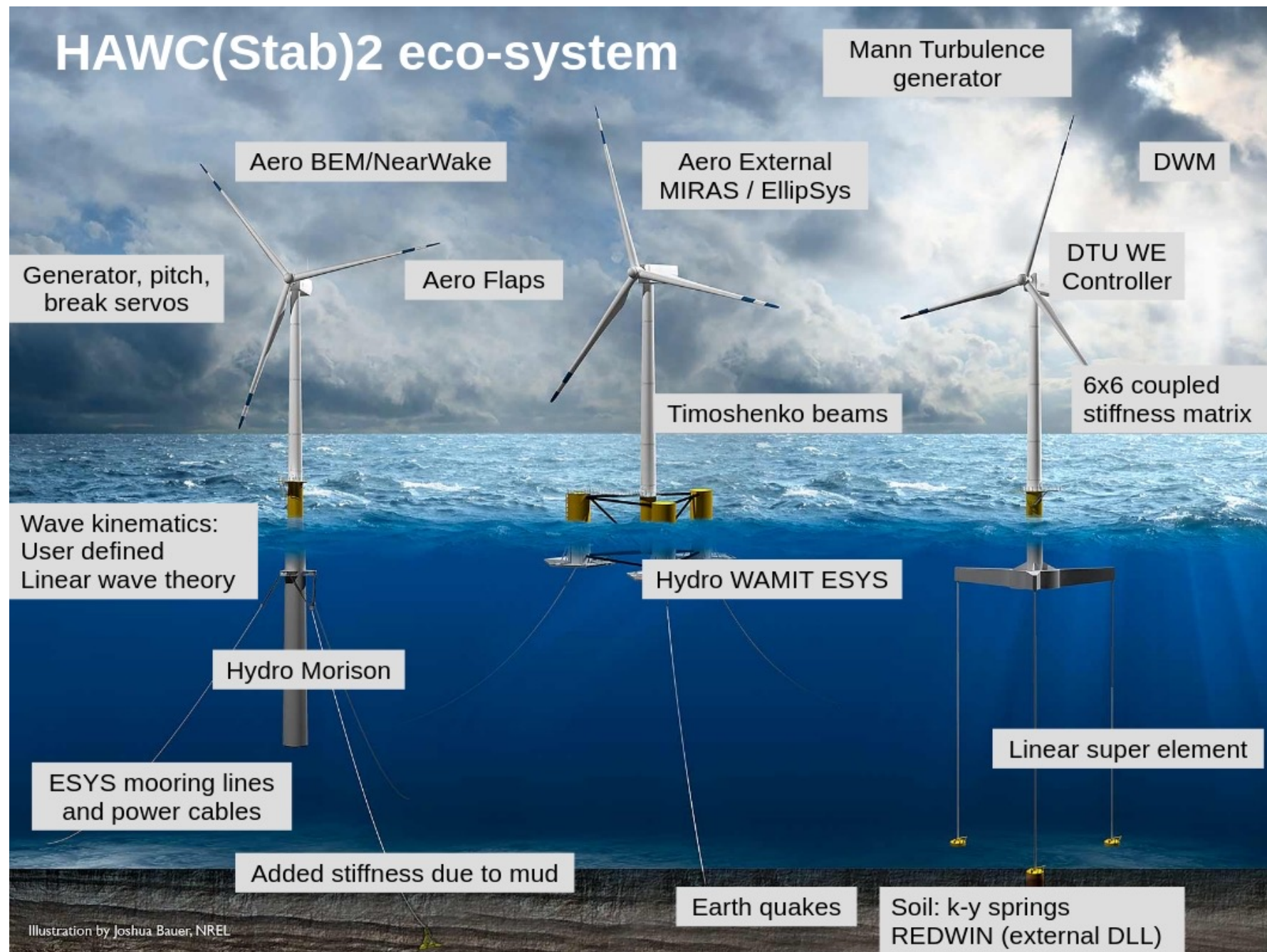
General non-linear time domain response

DTU WE Controller (DLLs)

External Systems (ESYS)

3D Visualisation

Pre- and post-processing



HAWC2: Examples and applications




MINGYANG SMART ENERGY
 明阳智能
 地蕴天成·能动无限

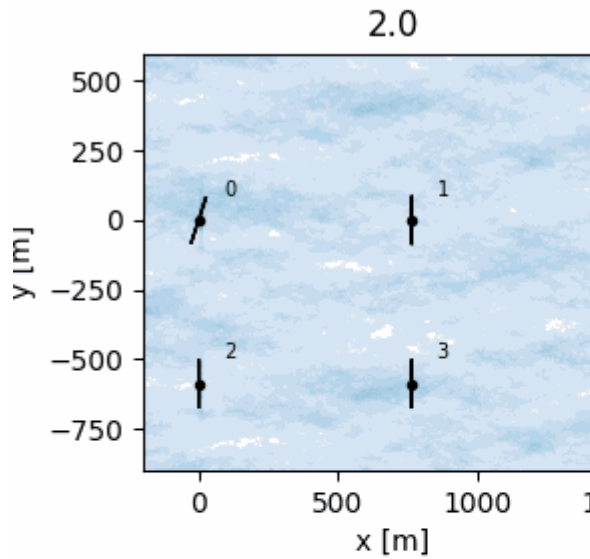


Vestas

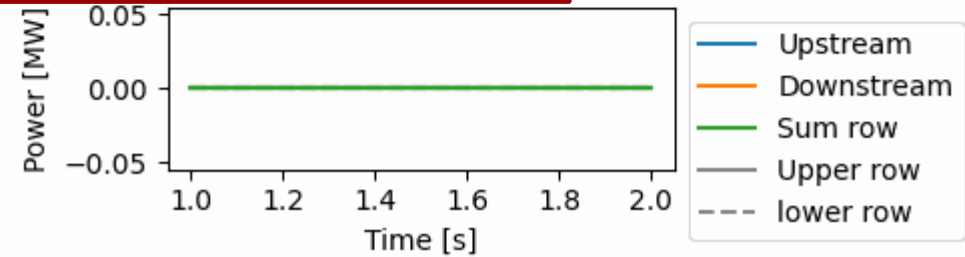
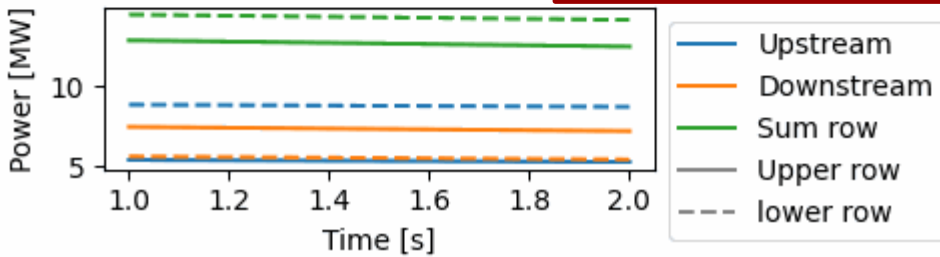
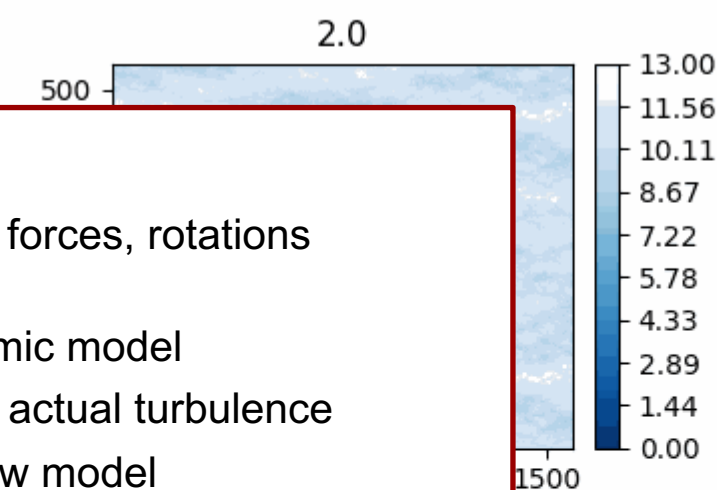


```
wts = PyWakeWindTurbines(
    x=wt_x, y=wt_y,
    windTurbine=DTU10MW())
wts.yaw = [-17,0,0,0]
```

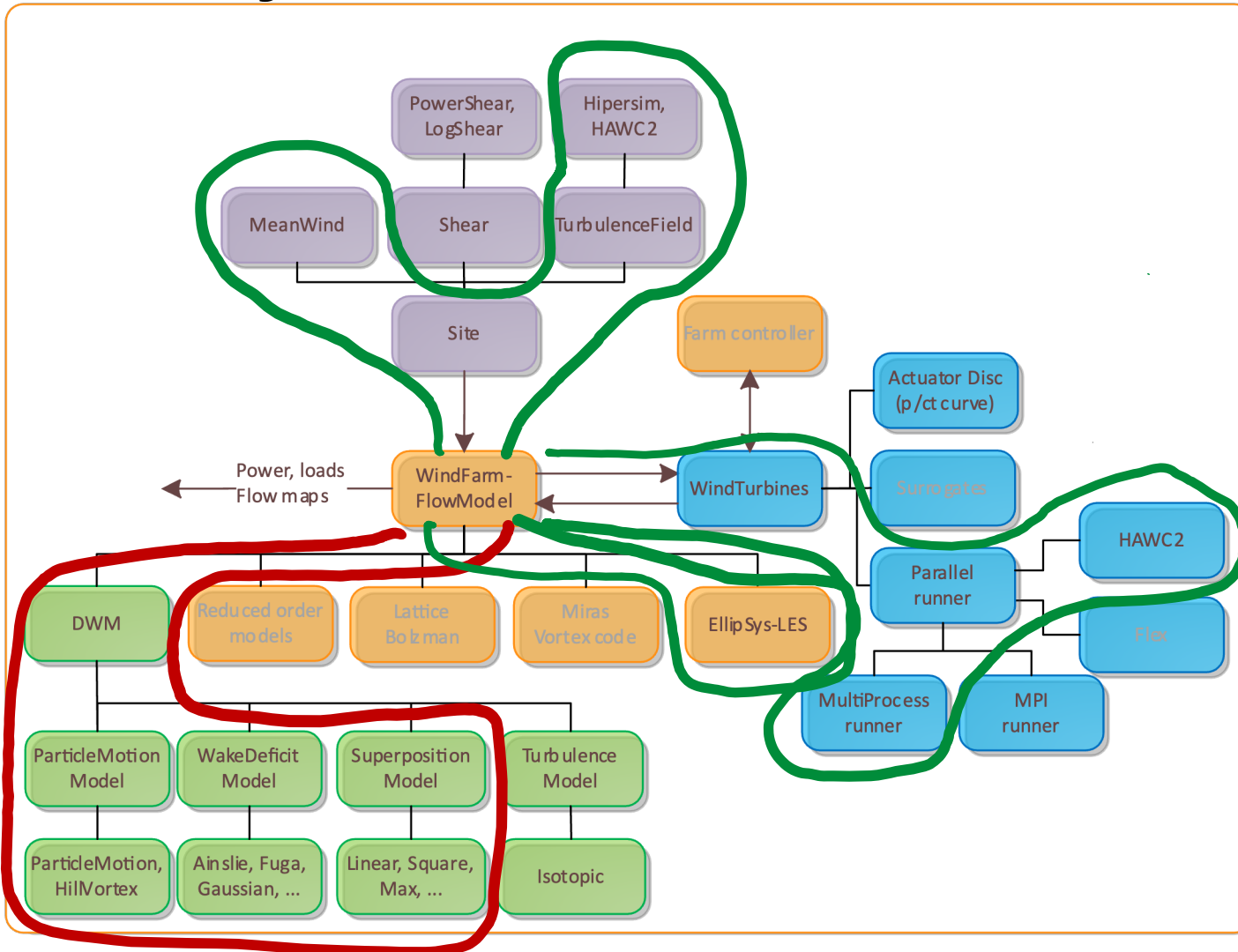
```
wts = HAWC2WindTurbines(
    x=wt_x, y=wt_y,
    htc_filename_lst=['htc/DTU_10MW_RWT_yaw-17.htc',
                    'DTU_10_MW/htc/DTU_10MW_RWT.htc'],
```



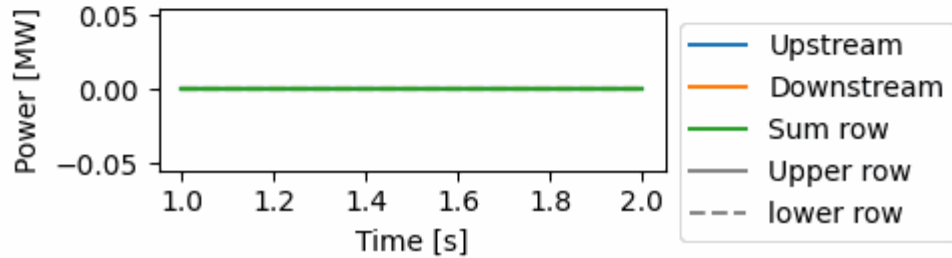
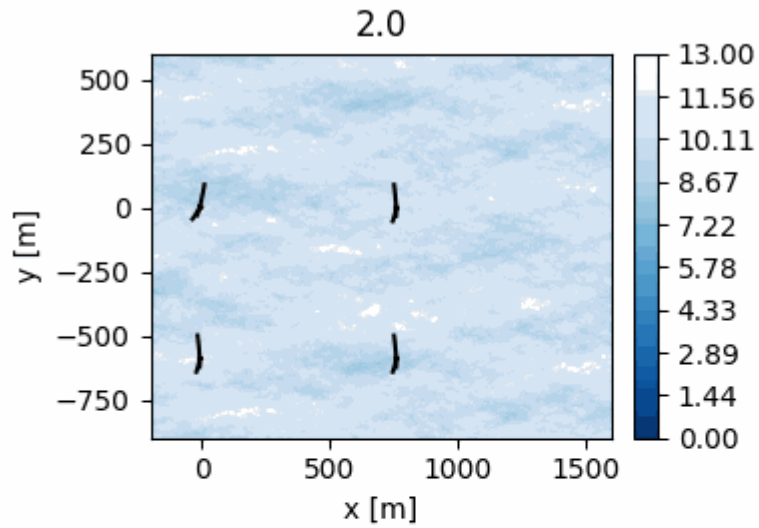
- Full aero elastic model
- Structure model including forces, rotations deflection, etc.
 - Medium fidelity aerodynamic model
 - Each blade sees the actual turbulence
 - Advanced skew inflow model
 - Effects of variations over the rotor
 - Load evaluation



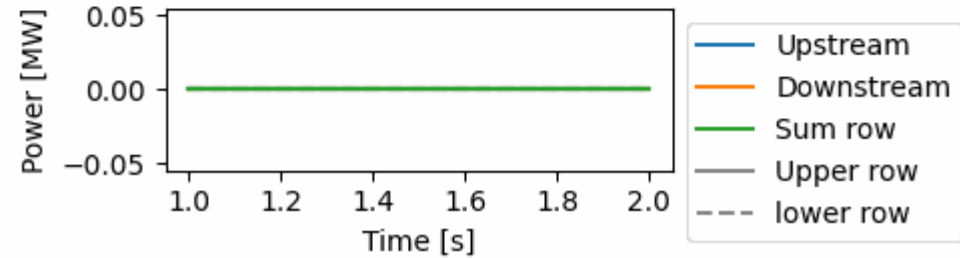
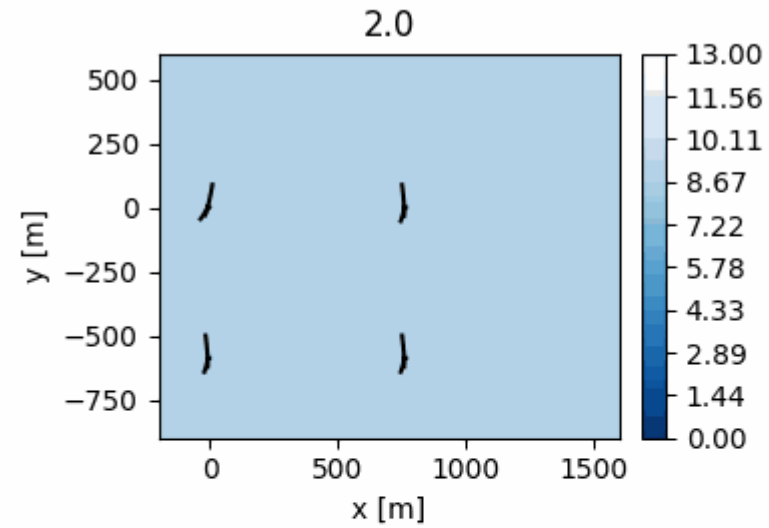
Dynamiks, modular, flexible and multifidelity



```
fs = DWMFlowSimulation(
    windTurbines=wts,
    site=site)
```

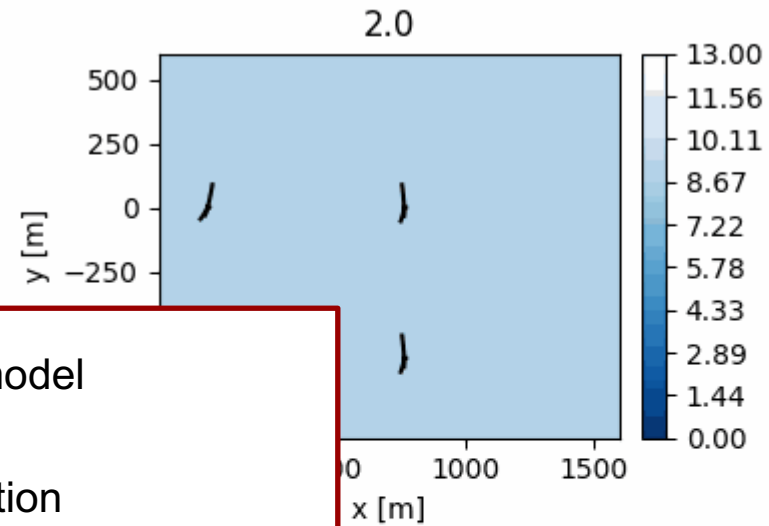
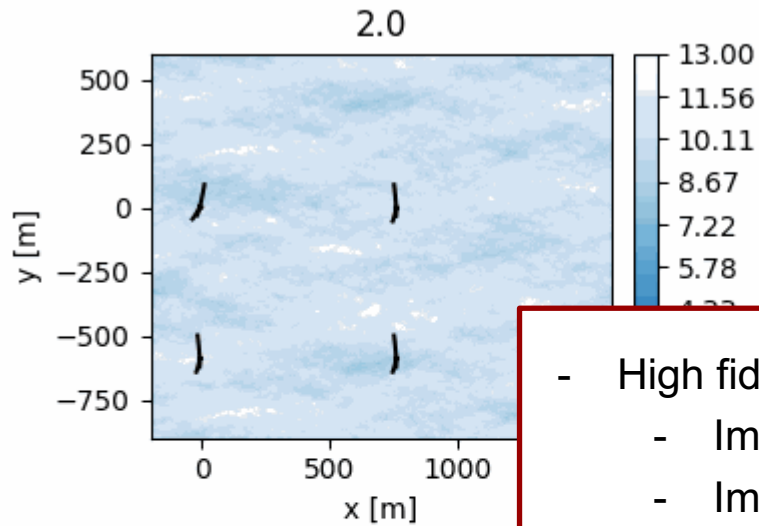


```
fs = Ellipsys3D_MPI_FlowSimulation(
    windTurbines=wts,
    input_file="./input.dat")
```

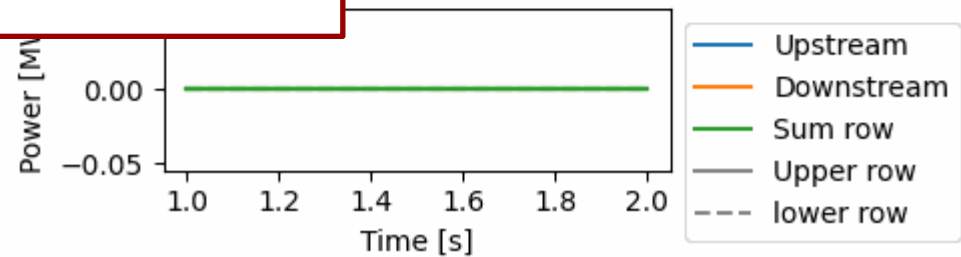
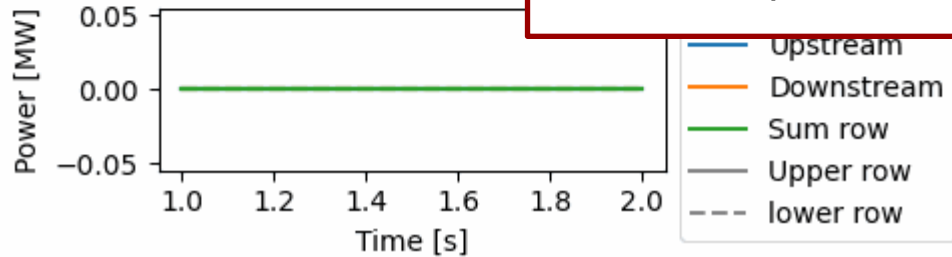


```
fs = DWMFlowSimulation(
    windTurbines=wts,
    site=site)
```

```
fs = Ellipsys3D_MPI_FlowSimulation(
    windTurbines=wts,
    input_file="./input.dat")
```



- High fidelity CFD LES flow model
 - Implicit wake deficit
 - Implicit wake superposition
 - Implicit wake-added turbulence
 - Implicit wake deflection



What if

What if:

- Wind direction changes

Then:

- Yaw controller estimates wind direction from the turbulent wind speed
- Yaw controller waits to ensure that the mean wind direction really has changed
- Yaw controller realize that the wind is aligned with the row
- Yaw controller gives a 18deg misalignment setpoint to the yaw actuator
- Yaw actuator starts to yaw
- Turbine reaches its misaligned angle
- Wake starts to deflect
- Deflected wake advects to the downstream turbine
- Downstream turbine starts to produce more power

What if

What if:

- Wind direction changes

Then:

- Yaw controller estimates wind direction from the turbulent wind speed
- Yaw controller waits to ensure that the measured direction really has changed
- Yaw controller realize that the wind is aligned with the row
- Yaw controller gives a 18deg measured setpoint to the yaw actuator
- Yaw actuator starts to yaw
- Turbine reaches its measured angle
- Wake starts to deflect
- Deflected wake is directed to the downstream turbine
- Downstream turbine starts to produce more power

Wind direction changes again