



Overview of DAKOTA Project

(from the software perspective)

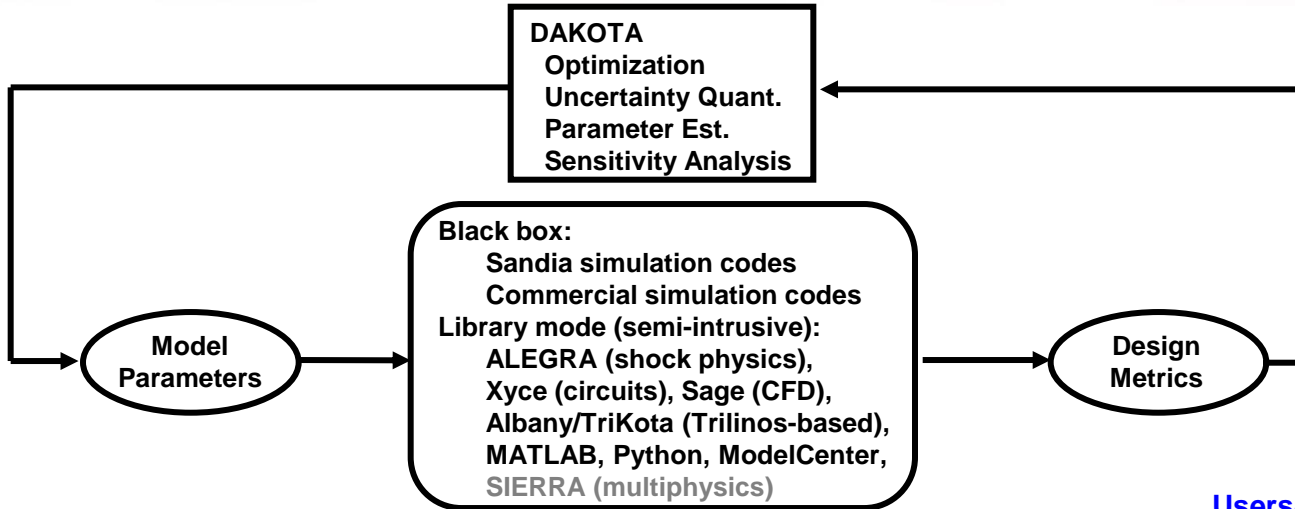
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Optimization and Uncertainty Quantification Department (1441)

NREL

December 14, 2010

- **Capability overview**
- **Advanced deployment efforts**

DAKOTA Project



Iterative systems analysis
Multilevel parallel computing
Simulation management

<http://dakota.sandia.gov>

Users/Ref/Dev Manuals + training mats. online

Began as optimization LDRD in **1994**

Team: 5-10 core personnel in NM/CA + TPL developers

Releases: Major/Interim, Stable/VOTD; *5.1 release due 12/10*

DAKOTA Training: 8 sessions (~140 students) since 5.0;
26 sessions (~500 students) total since 2001.

2009 Outreach: Minitutorials at IMAC, SIAM CS&E;
SA/UQ short courses at NASA Langley, AFRL WPAFB.

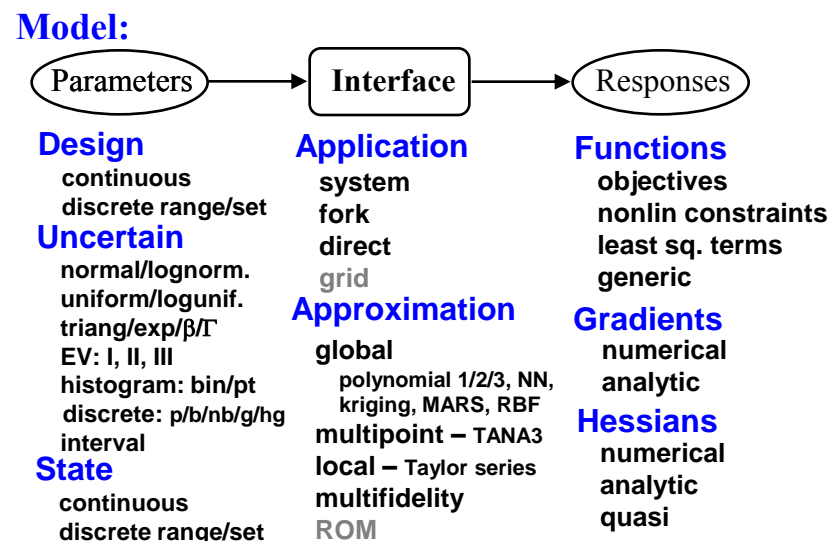
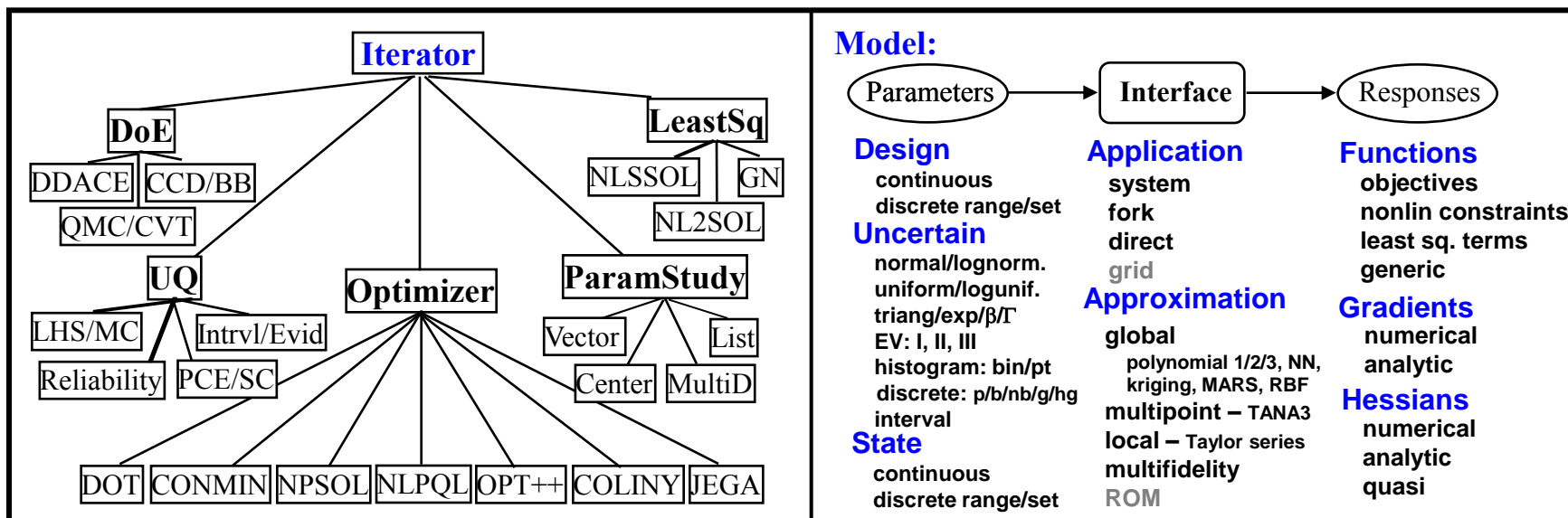
Modern SQE: Linux/Unix, Mac, Windows; Nightly builds/testing;
subversion, TRAC, Cmake; Top 2008 SQE score

GNU LGPL: free downloads worldwide
(~6500 total ext. registrations, ~3500 distributions last yr.)

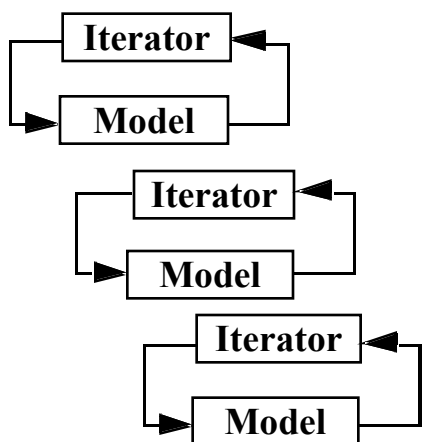
Community development: open checkouts now avail (→ PSAAP)

Community support: dakota-users, dakota-developers

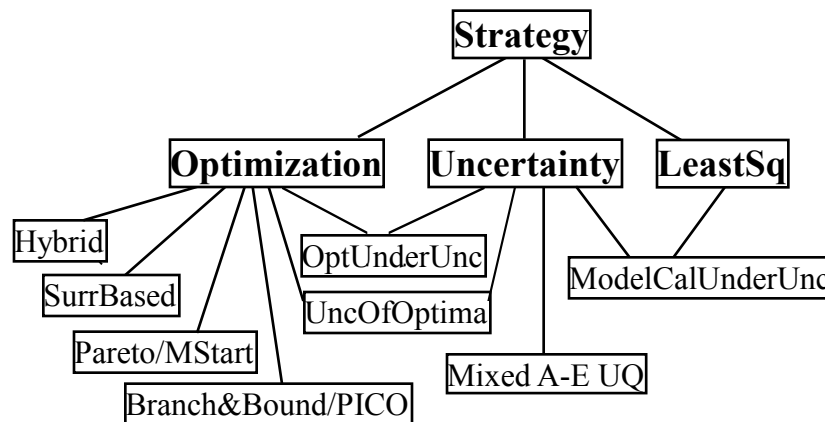
C++ Framework



Strategy: control of multiple iterators and models



- Coordination:**
 Nested
 Surrogate
 Recast
 Sequential/Concurrent
 Adaptive/Interactive
- Parallelism:**
 Asynchronous local
 Message passing
 Hybrid
 4 nested levels with
 Master-slave/dynamic
 Peer/static



Core Methods

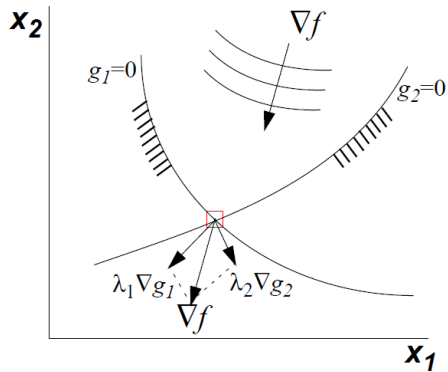


Optimization: minimize/maximize objective(s) subject to constraints

Karush-Kuhn-Tucker conditions:

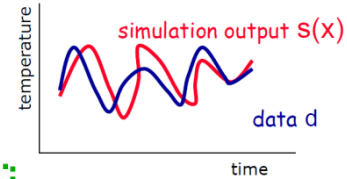
$$\nabla f - \sum_i \lambda_i \nabla g_i = 0$$

Achieve vector balance: objective fn grad contained within feasibility cone



Model Calibration/Parameter Estimation:

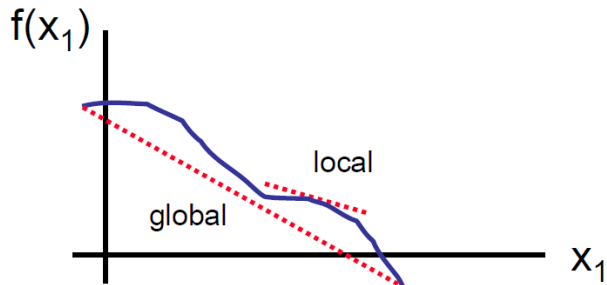
use nonlinear least squares to minimize errors between model and data



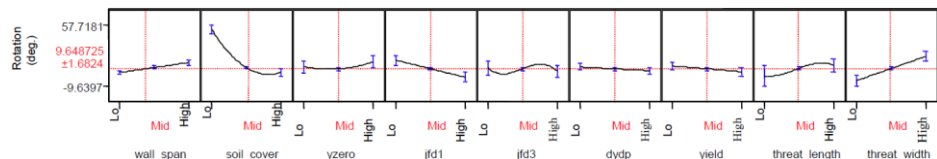
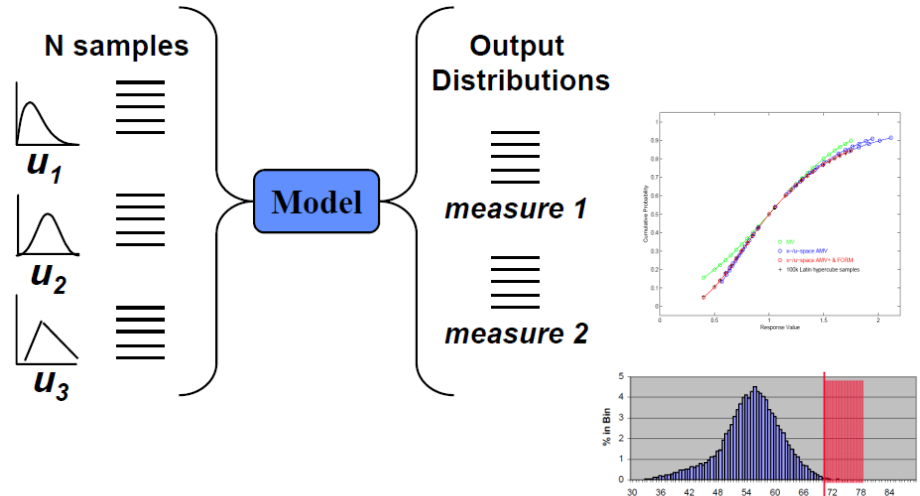
$$f(x) = \sum_{i=1}^n (s_i(x) - d_i)^2$$

Simulation output that depends on X Given data


Sensitivity Analysis: identify most influential set of parameters for key response metrics



Uncertainty Quantification: quantify effect of random variables on key response metrics



Uncertainty Quantification Algorithms @ SNL: New methods bridge robustness/efficiency gap

	Production	New	Under dev.	Planned	Collabs.
Sampling	Latin Hypercube, Monte Carlo	Importance, Incremental		Bootstrap, Jackknife	FSU
Reliability	<i>Local:</i> Mean Value, First-order & second-order reliability methods (FORM, SORM)	<i>Global:</i> Efficient global reliability analysis (EGRA)		gradient-enhanced EGRA	<i>Local:</i> Notre Dame, <i>Global:</i> Vanderbilt
Stochastic expansion	<div style="border: 1px solid blue; padding: 5px; display: inline-block;"> Adv. Deployment  Fills Gaps </div>	Tailored polynomial chaos & stochastic collocation with extended basis selections	p-adaptive, adjoint gradient-enhanced	h-adaptive, hp-adaptive, discrete, multi-physics	Stanford, Purdue, Austr. Natl., FSU
Other probabilistic		Random fields/ stochastic proc.		Dimension reduction	Cornell, Maryland
Epistemic	Interval-valued/ Second-order prob. (nested sampling)	Opt-based interval estimation, Dempster-Shafer	Bayesian	Imprecise probability	LANL, Applied Biometrics
Metrics & Global SA	Importance factors, Partial correlations	Main effects, Variance-based decomposition	Stepwise regression		UNM

Research: Tailoring & Adaptivity


Generalized Polynomial Chaos Expansions

Approximate response w/ spectral proj. using orthogonal polynomial basis fns

i.e.

$$R = \sum_{j=0}^P \alpha_j \Psi_j(\xi)$$

using

$$\begin{aligned} \Psi_0(\xi) &= \psi_0(\xi_1) \psi_0(\xi_2) = 1 \\ \Psi_1(\xi) &= \psi_1(\xi_1) \psi_0(\xi_2) = \xi_1 \\ \Psi_2(\xi) &= \psi_0(\xi_1) \psi_1(\xi_2) = \xi_2 \\ \Psi_3(\xi) &= \psi_2(\xi_1) \psi_0(\xi_2) = \xi_1^2 - 1 \\ \Psi_4(\xi) &= \psi_1(\xi_1) \psi_1(\xi_2) = \xi_1 \xi_2 \\ \Psi_5(\xi) &= \psi_0(\xi_1) \psi_2(\xi_2) = \xi_2^2 - 1 \end{aligned}$$

- **Nonintrusive:** estimate α_j using sampling (expectation), pt collocation (regression), tensor-product quadrature, Smolyak sparse grids, or cubature (numerical integration)

$$\alpha_j = \frac{\langle R, \Psi_j \rangle}{\langle \Psi_j^2 \rangle} = \frac{1}{\langle \Psi_j^2 \rangle} \int_{\Omega} R \Psi_j \varrho(\xi) d\xi$$

$$\langle \Psi_j^2 \rangle = \prod_{i=1}^n \langle \psi_{m_i}^2 \rangle$$

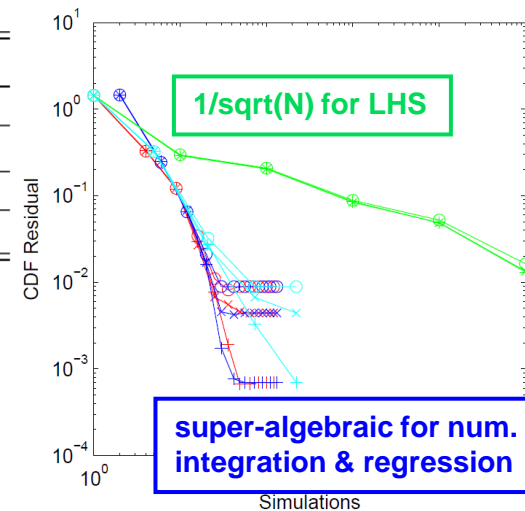
Generalized PCE (Wiener-Askey + numerically-generated)

- **Taylor basis:** optimal basis selection leads to exponential convergence rates

Distribution	Density function	Polynomial	Weight function	Support range
Normal	$\frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}}$	Hermite $He_n(x)$	$e^{-\frac{x^2}{2}}$	$[-\infty, \infty]$
Uniform	$\frac{1}{2}$	Legendre $P_n(x)$	1	$[-1, 1]$
Beta	$\frac{(1-x)^\alpha (1+x)^\beta}{2^{\alpha+\beta+1} B(\alpha+1, \beta+1)}$	Jacobi $P_n^{(\alpha, \beta)}(x)$	$(1-x)^\alpha (1+x)^\beta$	$[-1, 1]$
Exponential	e^{-x}	Laguerre $L_n(x)$	e^{-x}	$[0, \infty]$
Gamma	$\frac{x^\alpha e^{-x}}{\Gamma(\alpha+1)}$	Generalized Laguerre $L_n^{(\alpha)}(x)$	$x^\alpha e^{-x}$	$[0, \infty]$

Additional bases generated numerically via Golub-Welsch

- **Taylor expansion type/order/range:**
 - Total order \rightarrow tensor and sum of tensor expansions
 - Dimension p-refinement: anisotropic tensor/sparse grids
 - Domain h-refinement: discretization of random domain



ASCR Wind Turbine UQ



New DOE ASCR Project (Office of Science): FY2010-2012

Short term:

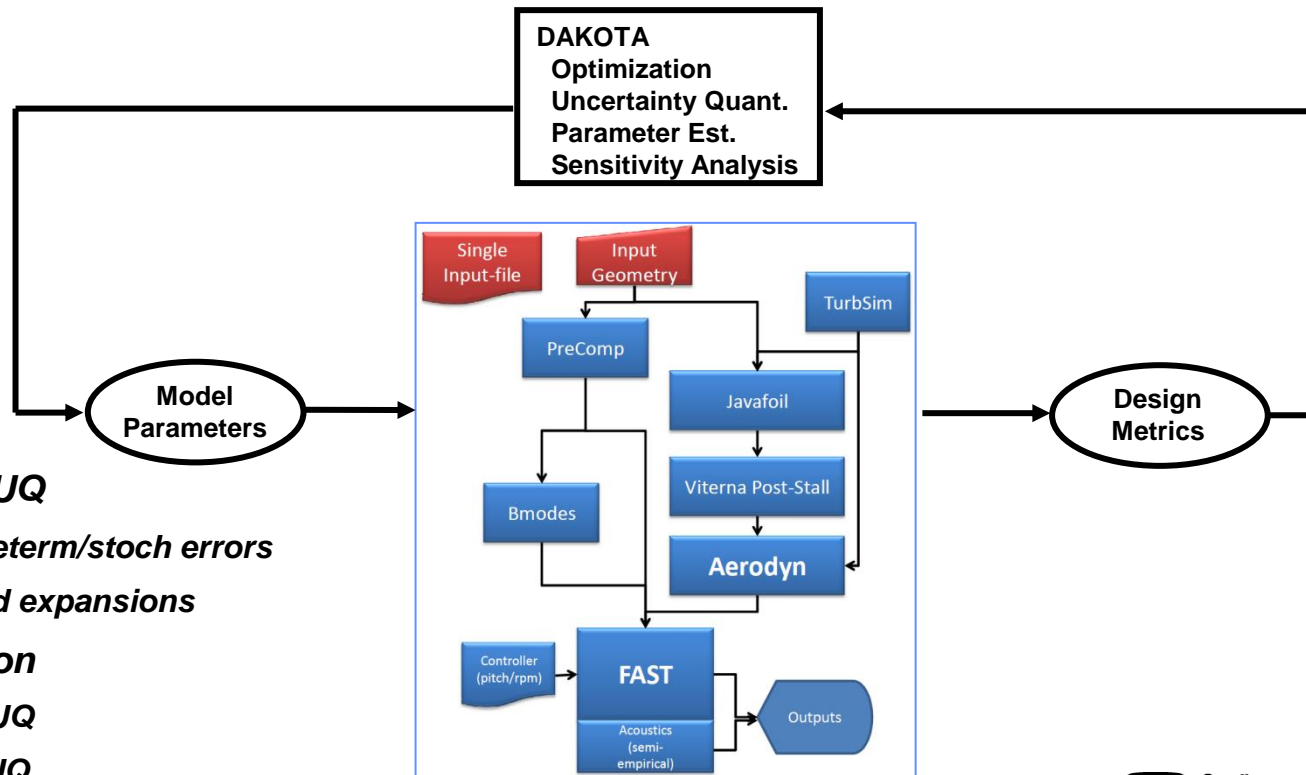
- *MATLAB management of NREL design tool ensemble (“EOLO”, Sandia wind group)*

Longer term:

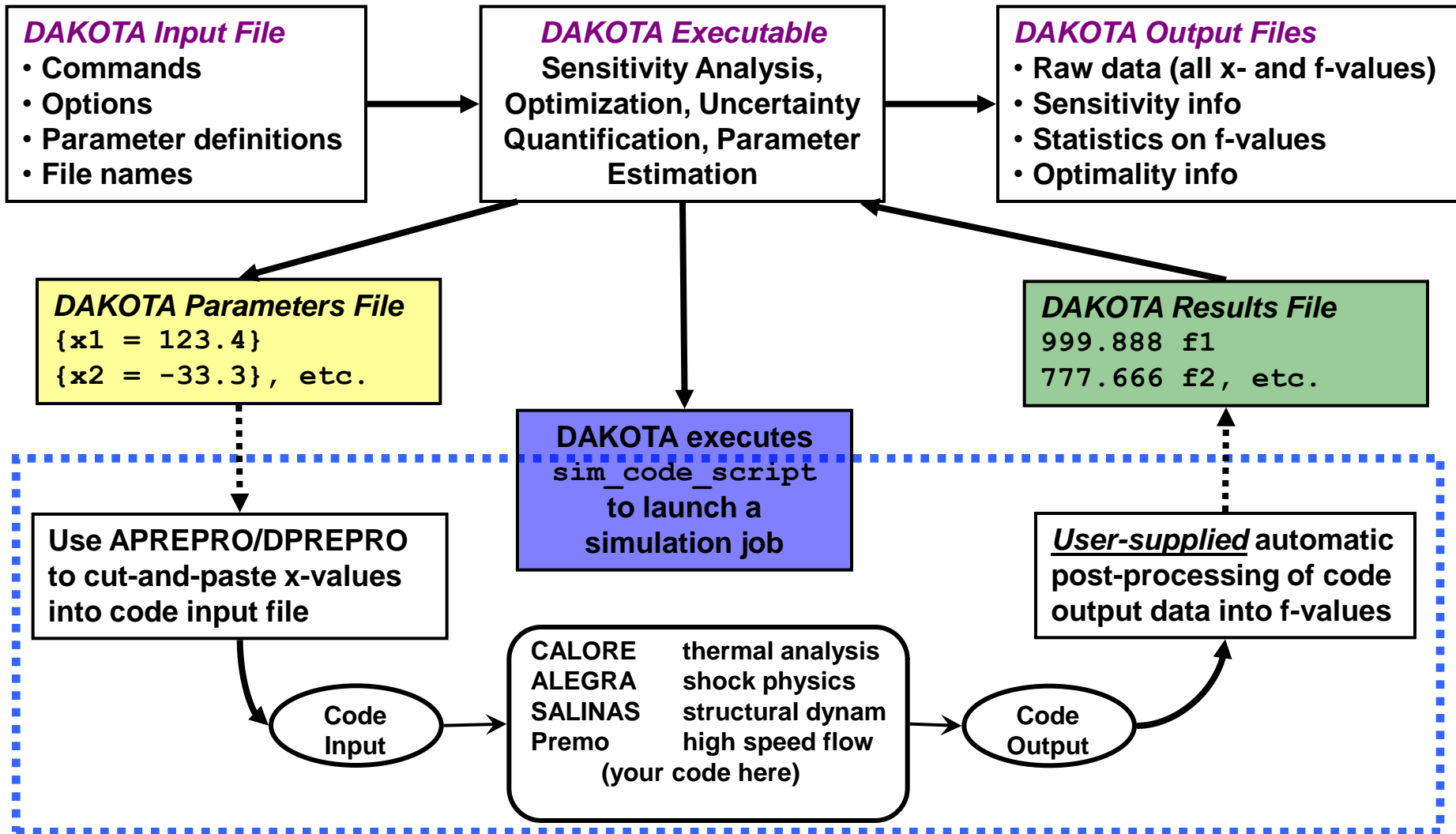
- *CFD with Joe (Stanford) and FSI with SIERRA/Aria (Sandia)*

UQ Research goals

- **Inner core: probabilistic UQ**
 - *Adjoint EE → balance of determ/stoch errors*
 - *Adaptive, adjoint-enhanced expansions*
- **Aggregation & Data Fusion**
 - *Mixed Aleatory/Epistemic UQ*
 - *Model Form: multifidelity UQ*
 - *Data fusion: Bayesian inference → BMA*

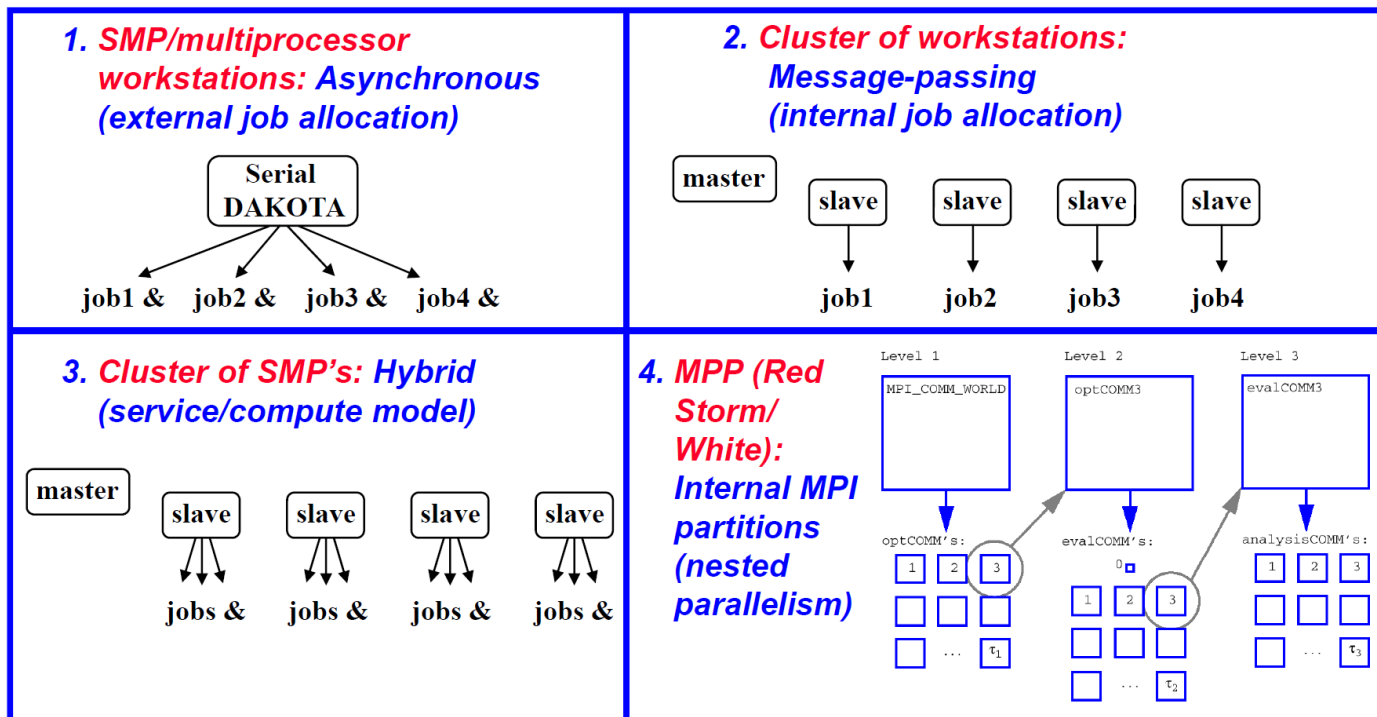


Simulation Management (Black Box case)



Parallelism Options: Multicore Desktops to MPP

1. **Algorithmic coarse-grained:** concurrency in data requests:
 - Iterators: Gradient-based, Nongradient-based, Surrogate-based
 - Strategies with concurrent Iterators: Multi-start, Pareto, Hybrid
 - Nested Models: OUU/MCUU, Mixed UQ
2. **Algorithmic fine-grained:** computing the internal linear algebra of an opt. algorithm in parallel
3. **Fn eval coarse-grained:** concurrent execution of separable simulations within each fn. eval.
4. **Fn eval fine-grained:** parallelization of the solution steps within a single analysis code

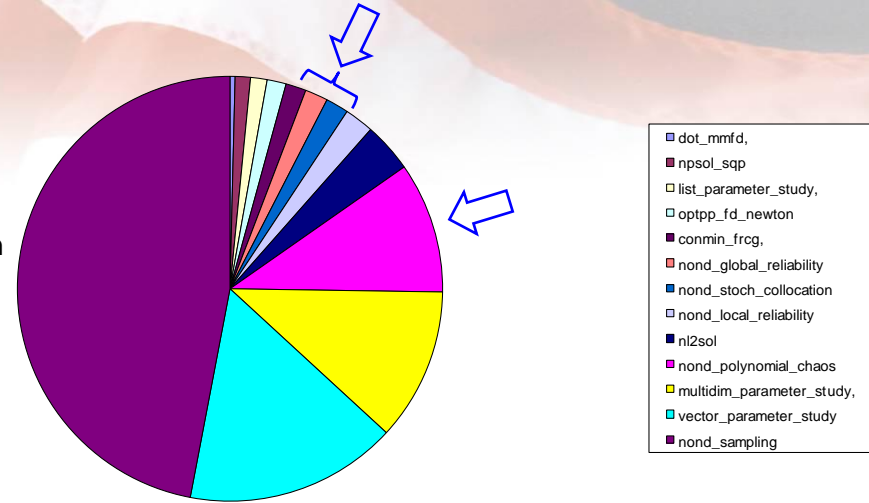


Deployment

Impact Sandia missions

- Technology insertion
 - ASC milestones
 - Early adopters

Jan/Feb 2010: 92% of DAKOTA invocations on SNL clusters were UQ or param studies, but new methods starting to reduce LHS dominance

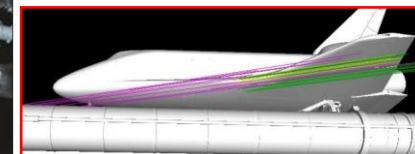
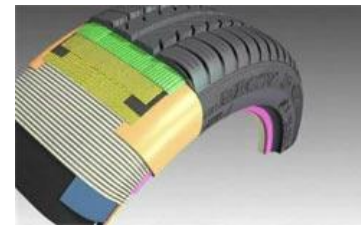
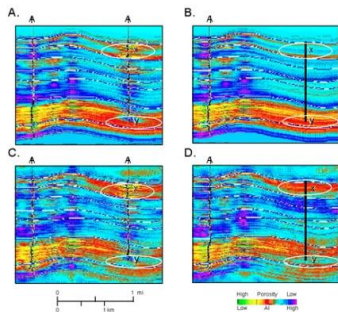
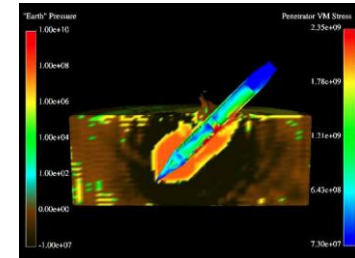
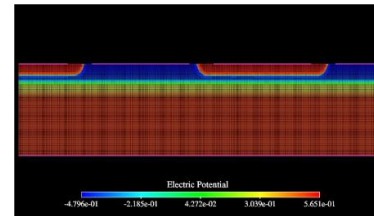
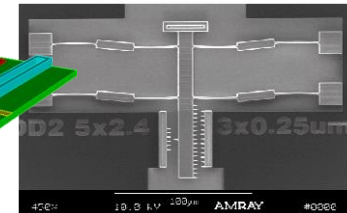
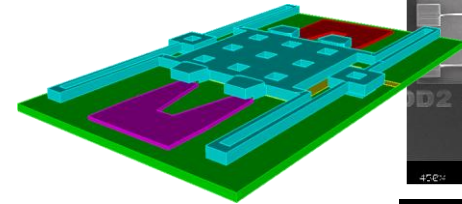


Partnerships

- Government: LLNL, LANL, ORNL, INL, NASA, DOD
- Industry: Lockheed Martin, Goodyear, Exxon Mobil
- University: MIT, Cornell, CU Boulder, Vanderbilt, USC, FSU, Notre Dame, VPISU, UNM
 - CSRI students/postdocs, faculty sabbaticals
 - ASC PSAAP: UT Austin (Bayesian), Purdue (cubature), UIUC (adaptive collocation), Caltech (global opt.), Michigan (gradient-enhanced interpolation), Stanford (adaptive collocation)

Address core usability barriers

- JAGUAR
- Library embedding



Deployment Initiative: JAGUAR User Interface

- Eclipse-based rendering of full DAKOTA input spec.
- Automatic syntax updates
- Tool tips, Web links, help
- Symbolics, sim. interfacing

- Flat text editor for experienced users
- Keyword completion
- Automatically synchronized with GUI widgets

- Simplified views for high-use applications (“Wizards”)

The screenshot displays the JAGUAR user interface, which is an Eclipse-based environment. It is divided into three main panes:

- Jaguar Editor:** Shows a tree view of the problem definition and execution sections. The tree includes STRATEGY, MODEL (with sub-nodes Model A and Model B), METHOD (with sub-nodes like ModelCalibration, non_d_global_reliability, u_gaussian_process, distribution, probability_levels, and gen_reliability_levels), VARIABLES (VarsSet1), INTERFACE (interface), and RESPONSES (RespSet1). A detailed view of the 'method' section is shown on the right, listing various options like 'Method set identifier', 'model_pointer', 'Output verbosity', 'Maximum iterations', 'Maximum function evaluations', 'Speculative gradients and Hessians', 'Convergence tolerance', 'Constraint tolerance', and 'Scaling flag'.
- Flat Text Editor:** Displays the DAKOTA input file 'dakota_textbook.in'. The code is as follows:

```
# DAKOTA INPUT FILE - dakota_textbook.in
strategy
  graphics
  single_method
method
  max_iterations 50
  convergence_tolerance 0.0001
  dot_mmfd
variables
  continuous_design 2
  initial_point 0.9 1.1
  lower_bounds 0.5 -2.9
  upper_bounds 5.8 2.9
  descriptors 'x1' 'x2'
interface
  analysis_drivers 'text_book'
  direct
responses
  num_objective_functions 1
  num_nonlinear_inequality_constraints 2
  numerical_gradients
  method_source
  dakota
  interval_type
  fd_step_size 0.0001
  no_hessians
```
- Dakota LHS Wizard:** A dialog box titled 'Specify Variables' for configuring the table contents. It includes a 'Uniform Uncertainty' section with 'samples' set to 100 and 'uniform_uncertain' set to 2. Below this is a table for defining variables:

	0.5	lower_bounds*	0.5	upper_bounds*	A	descriptors
0			1			'alpha'
100						'density'

At the bottom of the wizard, there are controls for adding, deleting, and duplicating rows, along with options to 'Generate samples' or 'Save input deck'. Navigation buttons '< Back', 'Next >', 'Finish', and 'Cancel' are located at the bottom right.

Impact: streamline problem set-up for user base, spanning novices to experts

Deployment Initiative: Embedding

Make DAKOTA natively available within application codes

- Streamline problem set-up, reduce complexity, and lower barriers
 - A few additional commands within existing simulation input spec.
 - Eliminate analysis driver creation & streamline analysis (e.g., file I/O)
 - Simplify parallel execution
- Integrated options for algorithm intrusion \implies

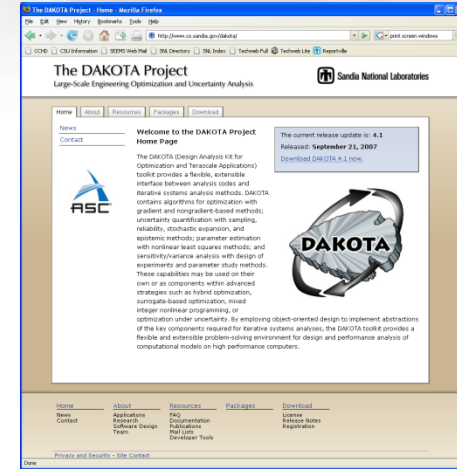
SNL Embedding

- Existing: Xyce, Sage, Albany (TriKOTA)
- New: ALEGRA, SIERRA (TriKOTA) \rightarrow STK

External Embedding

- Existing: ModelCenter, university applications
- New: QUESO (UT Austin), R7 (INL)
- Expanding our external focus:
 - GPL \rightarrow LGPL; svn restricted \rightarrow open network

Impact: eliminate custom set-up and support fully integrated opt. and UQ studies



ModelEvaluator Levels

Non-intrusive

ModelEvaluator: systems analysis

- All residuals eliminated, coupling satisfied
- DAKOTA optimization & UQ

Intrusive to coupling

ModelEvaluator: multiphysics

- Individual physics residuals eliminated; coupling enforced by opt/UQ
- DAKOTA opt/UQ & MOOCHO opt.

Intrusive to physics

ModelEvaluator: single physics

MOOCHO opt., STK/INOS UQ, NOX, LOGA

Concluding Remarks

DAKOTA provides a variety of core algorithms for iterative analysis:

- *Optimization*
- *Calibration*
- *Sensitivity Analysis*
- *Uncertainty quantification*

As well as advanced capabilities for

- *Multilevel parallel computing*
- *Manage multiple iterative methods, models of varying fidelity, nesting, recasting, etc.*
- *Emerging UQ methods: adaptive, adjoint-enhanced, multi-{fidelity,physics, scale}, mixed UQ*
- *Emerging algs. in other areas: OUU, SBO, MINLP, SA w/ PCE/SC, Nond. calibration*

Advanced deployment initiatives will “lower the bar” for adoption

- *JAGUAR*
- *Library embedding*

Expanding from NNSA to include energy missions: Wind, NE

Some lessons learned in open source framework development

- *Bound your mission space and manage scope creep*
 - *Focus on your core strengths and provide flexible APIs for others to use*
 - *Be selective on strategic partnerships*
- *Establish a support hierarchy and manage it effectively*
 - *Small teams may need to rely on community support for bottom tier*
- *Utilize modern CS tools (svn/git, cmake/scons, Trac) to simplify collaborative development*
- *Manage quality through sponsorship and review of external contributions*