

中国电力科学研究院有限公司

7th International Workshop on Grid Simulator Testing of Energy Systems and Wind Turbine Drivetrains

The Use of Grid Simulators in CEPRI and the

Development of 25MW Drivetrain Test Bench

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Department of Renewable Energy Research China Electric Power Research Institute (CEPRI) October 1st, 2024



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25MW Drivetrain Test Bench

China Electric Power Research Institute (CEPRI)



- A research institute directly under the State Grid Corporation of China (SGCC).
- 4 Chinese national key laboratories and 18 research departments, including the departments of power system, high voltage, renewable energy, energy storage, AI in power system, etc.



- Founded in 1951
- 2739 employees
- Beijing, Shanghai, Nanjing, Wuhan, Fuzhou...
- 2 academicians of Chinese Academy of Sciences
- 3 academicians of Chinese Academy of Engineering
- 10 national laboratories
- 11 provincial and ministerial laboratories
- 19 SGCC laboratories

Department of Renewable Energy Research

Focus on the prediction, schedule/dispatch, control and test of renewable power generation.
Research resources and wind power test bases include National key laboratory of renewable energy grid-integration, Zhangbei wind power test base, National offshore wind power test and research base (under construction), etc.



HiL simulation systems, Beijing

Zhangbei wind power test base, Hebei

National offshore wind power test and research base, Fujian (Completion expected by end 2024)



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25MW Drivetrain Test Bench

Grid Simulators in Use

IGBT-based grid simulators rated at 2MVA~10MVA (mostly mobile 6MVA and 10MVA), with parallel operation capability. Mainly used in wind turbine grid adaptability tests and fault ride-through tests.
IGCT-based 90MVA grid simulator developed for the 25MW drivetrain test bench.



Tests using mobile grid simulators

Large capacity grid simulator for the test bench

Grid Simulators in Use

6MVA~10MVA Grid Simulators



- Input: three-phase voltage source rectifiers connected to a multi-winding transformer.
- Output: cascading of H-bridge modules at each phase.



Specifications of grid simulators

Specifications	Values
Nominal voltage	35kV line-to-line
Power factor	-0.9 ~ 0.9
Voltage range	0 ~ 140%
Frequency range	45Hz ~ 66Hz
Voltage unbalance	0 ~ 10%
Voltage flicker Pst	0 ~ 10
Overload capability	110%: 1min 135%: protection
Harmonic voltage output capability	2 nd ~7 th ≤ 6%/10% 8 th ~25 th ≤ 3%/5%

Grid Simulator Tests in China

Grid Adaptability Test



- Inspired by the frequent tripping of wind turbines caused by railroad traction substations.
- Documents formed as NB/T 31054-2014, GB/T 36994-2018, IEC TS 61400-21-4 annex (CDTS stage).



Grid Adaptability Test



Test items Set points **Duration time** 0.90p.u. 30min Voltage deviation 1.10p.u. 30min 48.0Hz 30min **Frequency deviation** 51.5Hz 30min 2.0% 30min Three-phase voltage unbalance 4.0% 1min Voltage fluctuation and flicker $1.0 (P_{st})$ 10min 2.4% (3rd~25th odd) 2min each Harmonic voltage 1.2% (2nd~24th even) 2min each 0.16% (5th~95th) Interharmonic voltage 2min each

* Requirements may change in recent revisions.





Primary frequency regulation test example

Stable operation requirements in GB/T 36994-2018





Undervoltage and Overvoltage Ride-through

Undervoltage, overvoltage and cascaded voltage ride-through tests with grid simulators.

IQ_MV_Pos

IQ_MV_Pos

IQ_MV_Pos

I/Ib

I/Ib

1.4

1.2

1.0

0.8

0.6

0.4

0.2

0.0

-0.2

0.2

0.0

-0.2

-0.4

-0.6

1.6

1.2

0.8

0.4

0.0

-0.4

-0.8

-1.0

I/Ib





0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17

New Functions Development

Impedance Measurement

Positive and negative sequence impedance measurements within 1Hz~1250Hz.



Comparison between test devices







Comparison with cHiL simulation

 $(\mathbf{F}) \xrightarrow{\mathbf{F}} \mathbf{F}$

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 $Z_{pp}(f_p) = \frac{V_p(f_p)}{I_p(f_p)} \qquad Z_{nn}(f_p) = \frac{V_n(f_p - 2f_1)}{I_n(f_p - 2f_1)}$ $\begin{bmatrix} Z_{pp} & Z_{pn} \\ Z_{np} & Z_{nn} \end{bmatrix} = \begin{bmatrix} V_p^1 & V_p^2 \\ V_n^1 & V_n^2 \end{bmatrix} \begin{bmatrix} I_p^1 & I_p^2 \\ I_n^1 & I_n^2 \end{bmatrix}^{-1}$

Comparison between calculations

Grid Forming

Operate as a controllable load to validate the grid forming capability (as a voltage source) of the DUT.

GFM Test Items	Instruction	Grid O Simulator	Dn-Grid Mode
On-Grid Mode	CB1 closed,CB2 and CB3 opened, Load simulator is bypassed, GFM DUT work on On-Grid mode	Grid CB1	GFM DUT Off-Grid Mode
Off-Grid Mode	CB1 opened,CB2 and CB3 closed, Load simulator working on current control mode, GFM DUT work on Off-Grid mode	Controller Load simulation CB2 mode	CB3
On-Grid to Off-Grid	CB1,CB2 and CB3 closed, Load simulator working on current control mode, and control the current of CB1 branch to zero, then open the CB1	DUT voltage	DUT current
Off-Grid to On-Grid	CB1 opened,CB2 and CB3 closed, Load simulator working on current control mode, then open the CB3 and close the CB1	Grid side input voltage	Grid side filter current

Voltage waveform of off-grid mode test

Current waveform of off-grid mode test

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Grid Forming

Grid forming tests in China currently also consider instantaneous inertia response, weak grid operation capability, mode switch between grid following and grid forming, and active damping capability, etc.

Grid forming test items

No.	Test items
1	Inertial response
2	Primary frequency regulation
3	Voltage phase angle response
4	Transient voltage support
5	Voltage and frequency adaptability
6	Low SCR operation capability
7	Active damping
8	Mode switch
9	Black start and supply the load

* Test items are not fully standardized yet.







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New Functions Development



Impedance Simulation and Voltage Phase Angle Jump

- Variation of the virtual grid impedance to simulate a weak grid environment with low SCR.
- Step change of the three-phase voltage phase angle.





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25MW Drivetrain Test Bench

General overview and objectives

Subsystems and specifications

Current status

Future plans



General Overview and Objectives

- National offshore wind power test and research base located in Fujian Province, southeast China.
- Include a 25MW drivetrain test bench, two 150m blade test benches (static and fatigue), and a test wind farm with 30+ onshore/offshore test locations.



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- 6 DOF load application system: drive motors and 5 DOF non-torque loading device.
- Grid simulation system: grid simulator with real-time digital simulation for pHiL.





Drive Motors

- Series connection of two synchronous motors with electrical excitation, nominal torque 35MNm.
- Adjustable tilt angle 6 ~ 10 degrees for adaptation to DUTs from different manufacturers.

Specifications of drive motor **Specifications** Values Nominal power 12.5MW×2 Nominal voltage 3.3kV Nominal speed 7rpm Max. speed 13rpm Nominal torque 35MNm Overload capability 130% Number of poles 120







Hydraulic tilt angle adjustment

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5 DOF Non-torque Loading Device

Loading with 6 hydraulic cylinders, max. static moment 90MNm, max. static force 11MN.

Specifications of 5 DOF load application

Specifications	Values
Max. static moment loading	90MNm
Max. dynamic moment loading	65MNm
Max. static radial force	11MN
Max. dynamic radial force	6.6MN
Max. static axial force	11MN
Max. dynamic axial force	6.6MN
Max. dynamic loading frequency	1Hz



5 DOF load decoupling under different tilt angles







Grid Simulator

- IGCT-based grid simulator with 2 ANPC rectifier input (34MVA) and 10 NPC inverter output (90MVA).
- Cascaded output with 35kV voltage. Common AC or DC bus connection with motor converters.



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Specifications	Values
Output power	90MVA
Nominal voltage	35kV
Frequency range	45Hz ~ 66Hz
Voltage range	0 ~ 150%
Voltage flicker Pst	1 ~ 10
Voltage unbalance	0 ~ 10%
Harmonic voltage generation	1Hz ~ 1250Hz
Combined harmonics injection	THD≤10% Accuracy ±0.5%



- Multi-level control architecture for the operation of the test bench.
- Enable mHiL and pHiL operation to accurately replicate the operation of DUT in the field.



Topology of test bench control

HiL system and data exchange

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WeMoLab

- Wind turbine simulation software developed by CEPRI, with support to mHiL operation.
- Co-simulation of aerodynamic-hydrodynamic-structural-electrical-control characteristics.











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Grid Integration Real-time Simulation

- Multi-core CPU simulators with FPGA for small-step power electronic simulation.
- Fiber-optic communication with the grid simulator controller to transmit references and measurements.



Developing of wind turbine connected by MMC-HVDC



Specifications of grid integration real-time simulator

Specifications	Values
Min. CPU simulation step size	20 <i>µ</i> s
Max. MMC modules in each bridge arm	512
Min. MMC simulation step size in FPGA	1 <i>µ</i> s
Latency from simulator to voltage amplification	Currently: ~800 <i>μ</i> s Aim: <500 <i>μ</i> s

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Equivalent Emulation of Operating Conditions

- Simplify the grid-integration system but equivalently keep some key characteristics.
- Mathematically express the system dynamics and integrated in the grid simulator controller.



Equivalently model the MMC-HVDC as a simplified system and mathematically analyze the dynamics for testing

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Current Status

- **□国电力科学研究院有限公司**
- Key subsystems manufacturing almost finished. System commissioning will start from Q4 2024.
- Plan to start the test of the first DUT (CSSC 18MW) from the first half of 2025.





Specifications of DUT		
Specifications	Values	
Nominal power	18MW	
Nominal speed	7rpm	
Max. speed	7.84rpm	
Blade length	126m	

















Testing of Multi-megawatt Wind Turbine for Grid Compliance and Certification

- Electrical characteristic test according to IEC 61400-21 and related documents.
- model validation and compliance assessment, referring to IEC 61400-27 and IEC TS 63102.



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Data Collection and Digital Twin Development

Digital twin systems of both the drivetrain test bench and the future offshore wind farms.



Data-driven modeling and simulation of the test bench



Digital twin of the offshore wind farm



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